

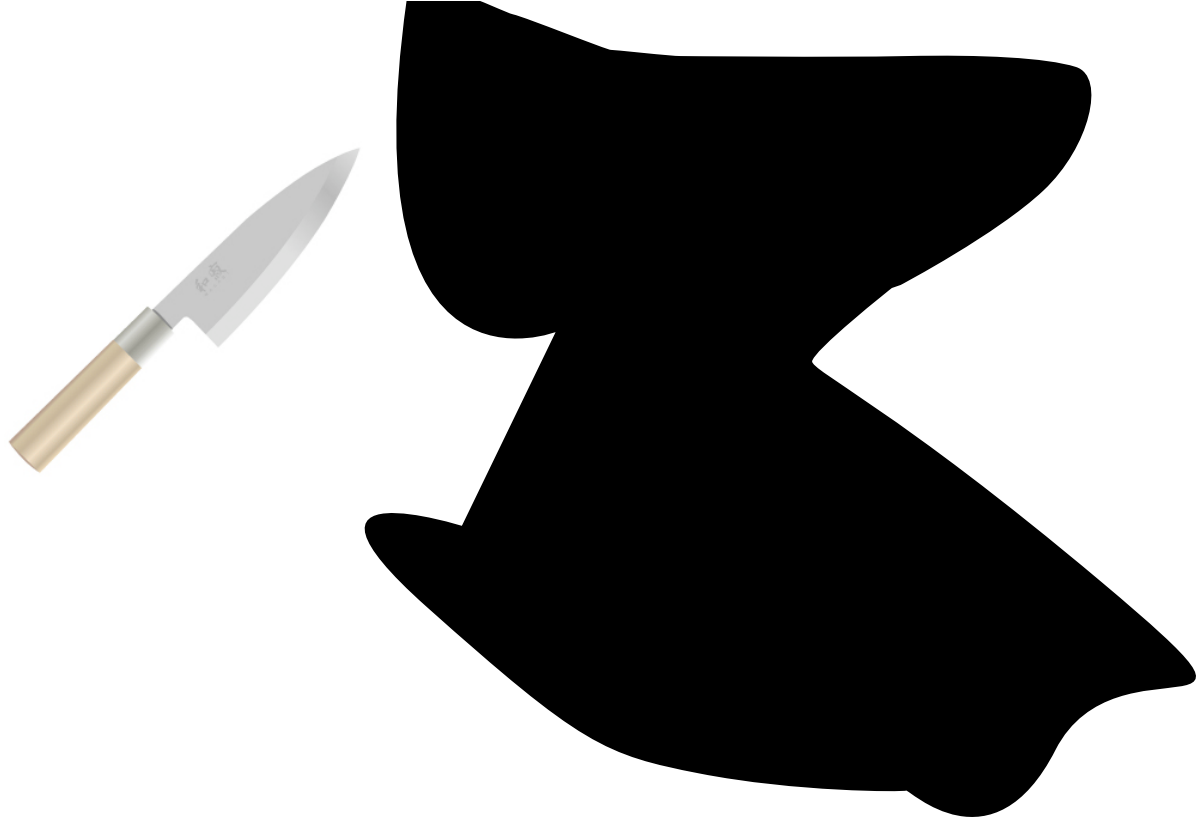
L5 5800

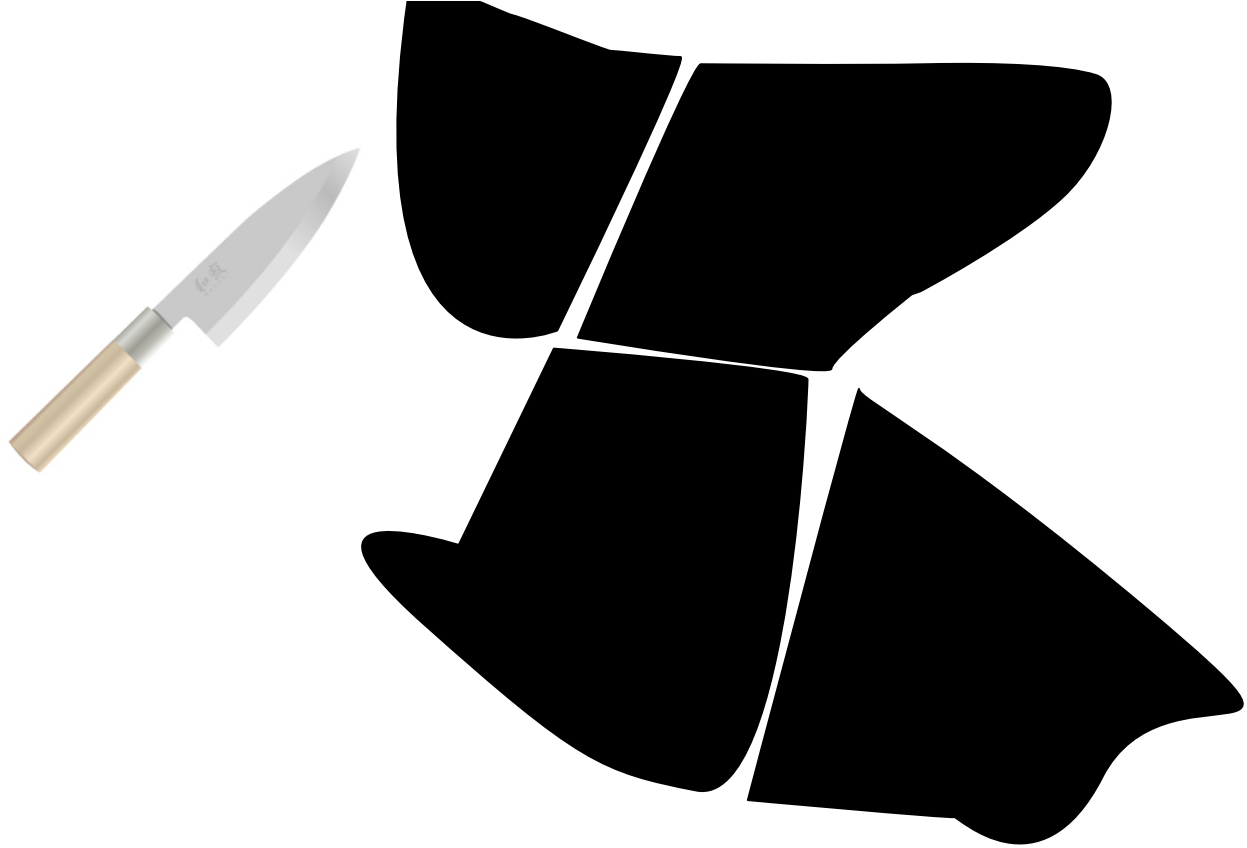
feb 1/3 2022

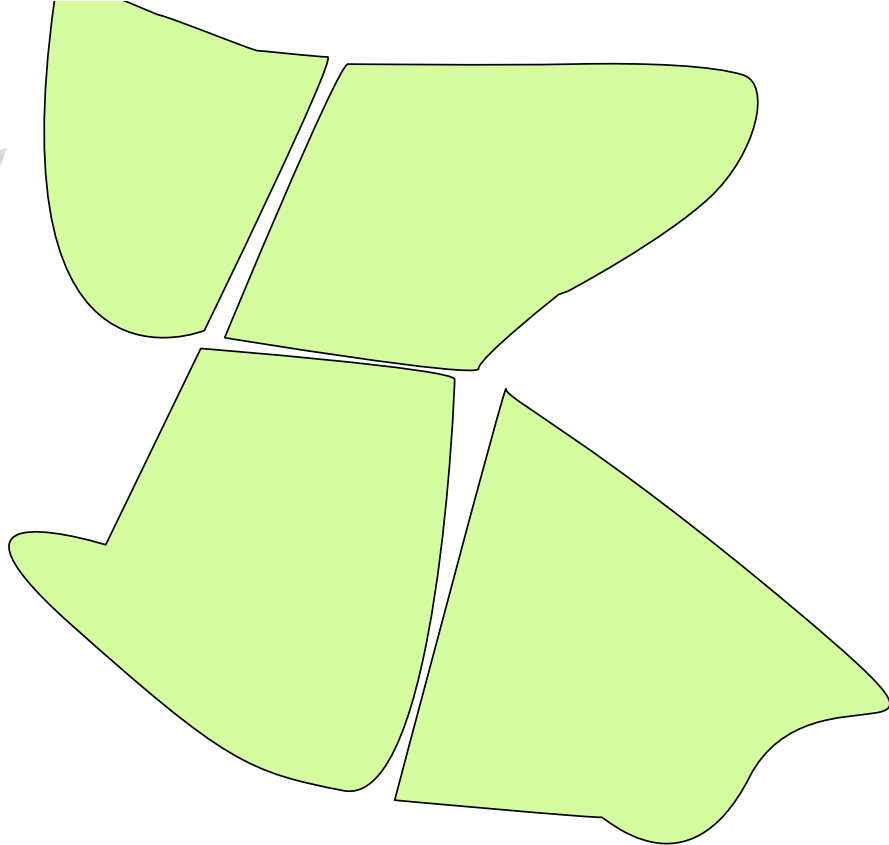
shelat

divide

& conquer



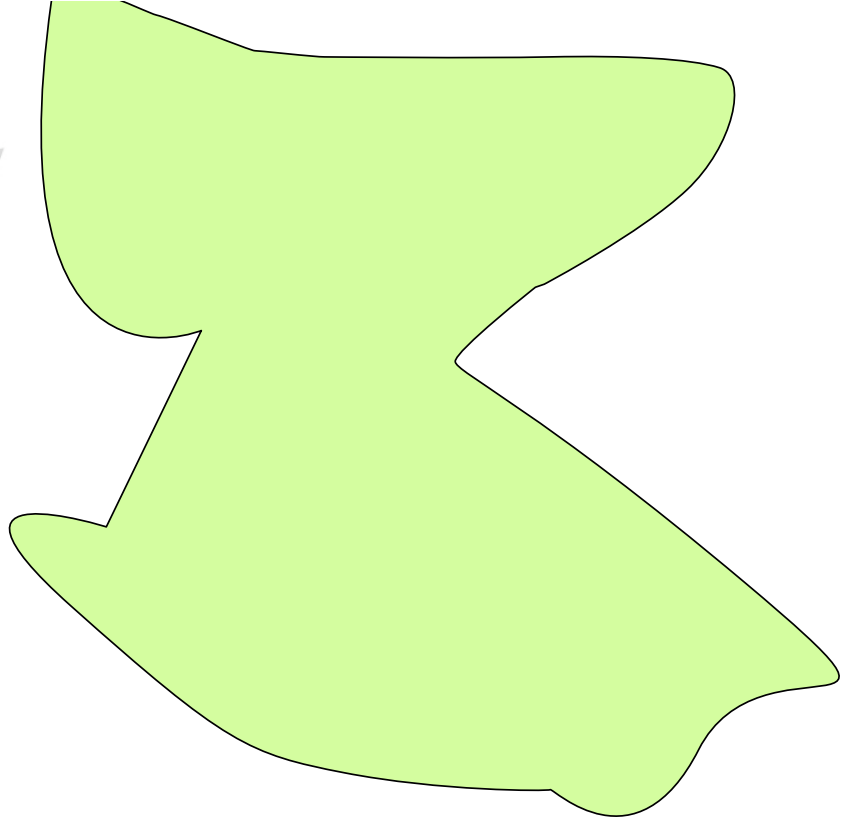




Zend
insight.



how to
recombine.



Examples we will discuss

- Merge sort
- Arbitrage
- Closest pair of points
- Median
- Matrix mult
- Fast Fourier Transform

Merge



merge-sort (A, p, r)

if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

merge (A, p, q, r)

MERGE($A[1..n], m$):

$i \leftarrow 1; j \leftarrow m + 1$

for $k \leftarrow 1$ to n

if $j > n$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

else if $i > m$

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

else if $A[i] < A[j]$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

else

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

for $k \leftarrow 1$ to n

$A[k] \leftarrow B[k]$

jeff erickson



merge-sort (A, p, r)

if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

merge(A, p, q, r)

MERGE($A[1..n], m$):

$i \leftarrow 1; j \leftarrow m + 1$

for $k \leftarrow 1$ to n

if $j > n$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

else if $i > m$

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

else if $A[i] < A[j]$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

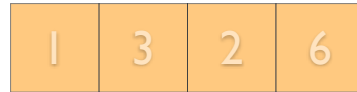
else

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

for $k \leftarrow 1$ to n

$A[k] \leftarrow B[k]$

jeff erickson



merge-sort (A, p, r)

if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

merge(A, p, q, r)

MERGE($A[1..n], m$):

$i \leftarrow 1; j \leftarrow m + 1$

for $k \leftarrow 1$ to n

if $j > n$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

else if $i > m$

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

else if $A[i] < A[j]$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

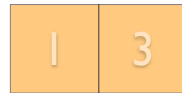
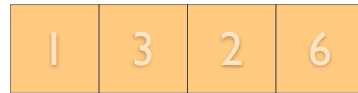
else

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

for $k \leftarrow 1$ to n

$A[k] \leftarrow B[k]$

jeff erickson



merge-sort (A, p, r)

if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

merge(A, p, q, r)

MERGE($A[1..n], m$):

$i \leftarrow 1; j \leftarrow m + 1$

for $k \leftarrow 1$ to n

if $j > n$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

else if $i > m$

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

else if $A[i] < A[j]$

$B[k] \leftarrow A[i]; i \leftarrow i + 1$

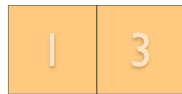
else

$B[k] \leftarrow A[j]; j \leftarrow j + 1$

for $k \leftarrow 1$ to n

$A[k] \leftarrow B[k]$

jeff erickson



merge-sort (A, p, r)

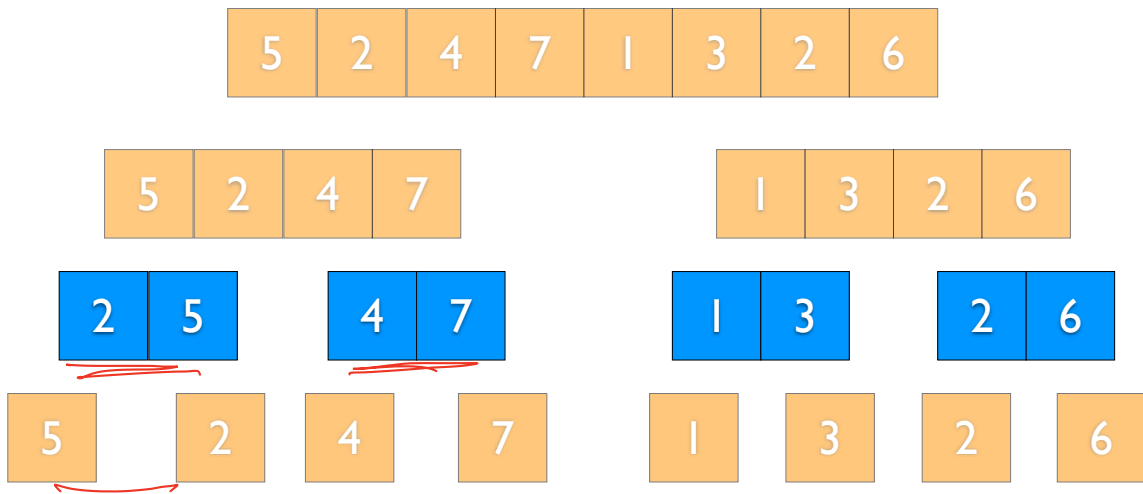
if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

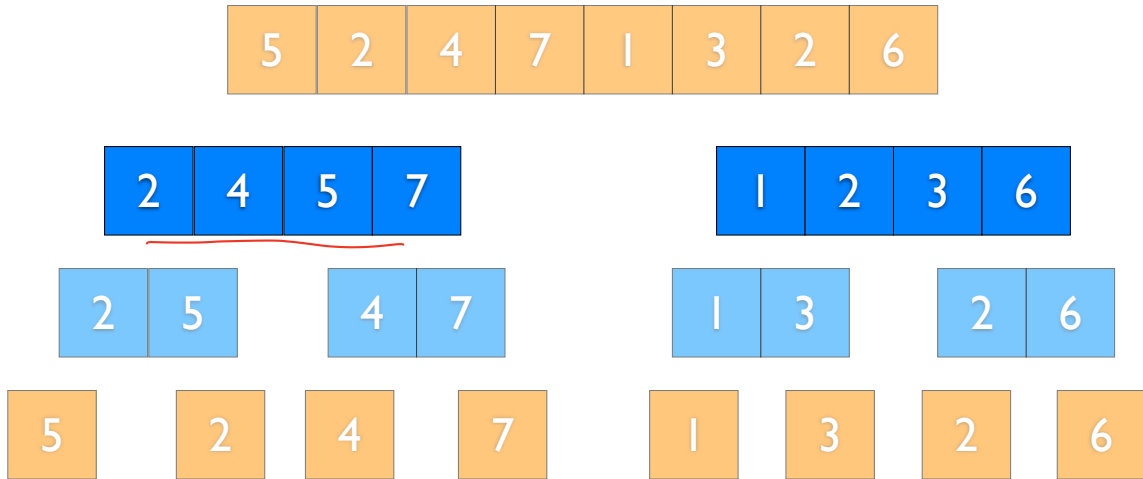
merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

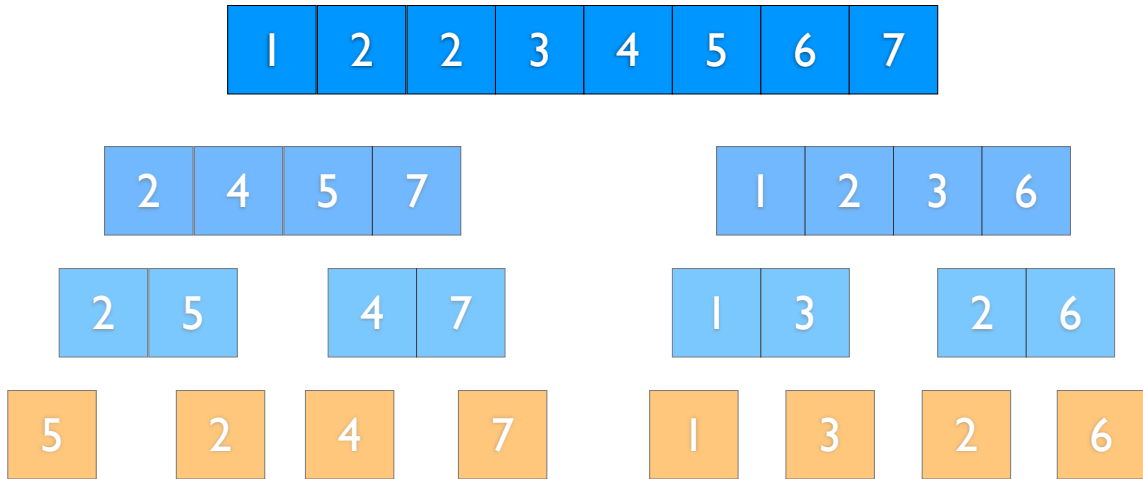
merge(A, p, q, r)



```
merge-sort ( $A, p, r$ )  
  if  $p < r$   
     $q \leftarrow \lfloor (p + r) / 2 \rfloor$   
    merge-sort ( $A, p, q$ )  
    merge-sort ( $A, q + 1, r$ )  
    merge( $A, p, q, r$ )
```



```
merge-sort ( $A, p, r$ )  
  if  $p < r$   
     $q \leftarrow \lfloor (p + r) / 2 \rfloor$   
    merge-sort ( $A, p, q$ )  
    merge-sort ( $A, q + 1, r$ )  
    merge( $A, p, q, r$ )
```



merge-sort (A, p, r)

if $p < r$

$q \leftarrow \lfloor (p + r) / 2 \rfloor$

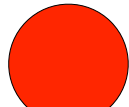
merge-sort (A, p, q)

merge-sort ($A, q + 1, r$)

merge(A, p, q, r)

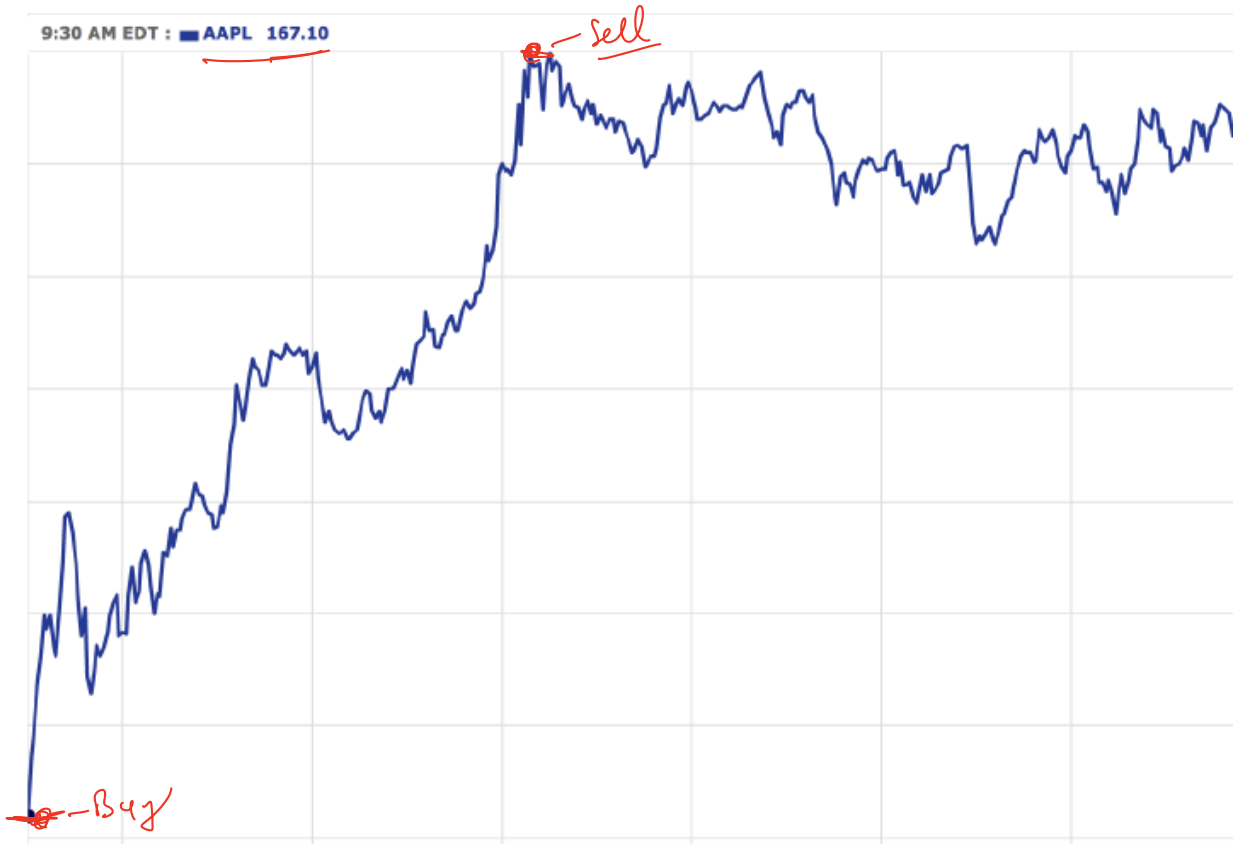
$\Theta(n)$

$$\begin{aligned} T(n) &= 2T(n/2) + \Theta(n) \\ &= \Theta(n \log n) \end{aligned}$$



arbitrage

9:30 AM EDT : AAPL 167.10





12:38 PM EDT : AIG 40.58

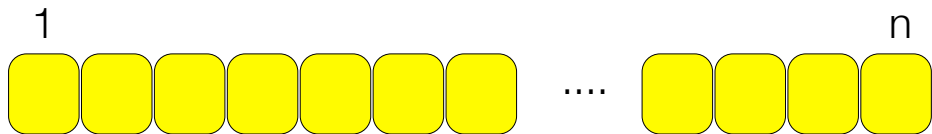


© 2008 Yahoo! Inc.

10:00 AM 11:00 AM 12:00 PM 1:00 PM 2:00 PM 3:00 PM 4:00 PM

→

input: array of n numbers



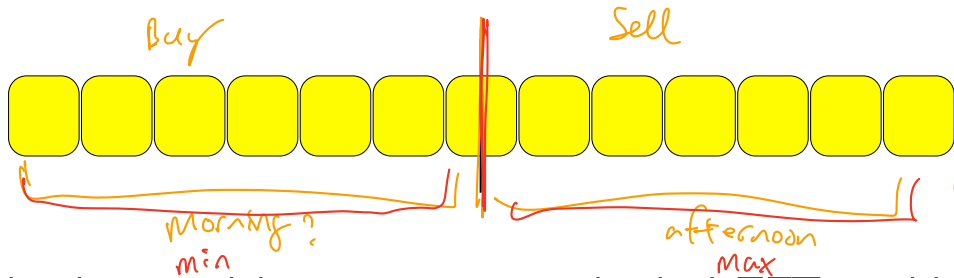
goal: is to find the best buy-sell opportunity.

i.e. the pair (i, j) such that $i < j$

and $A_j - A_i$ is the largest among

all pairs $(i, j) \in [1, n]^2$

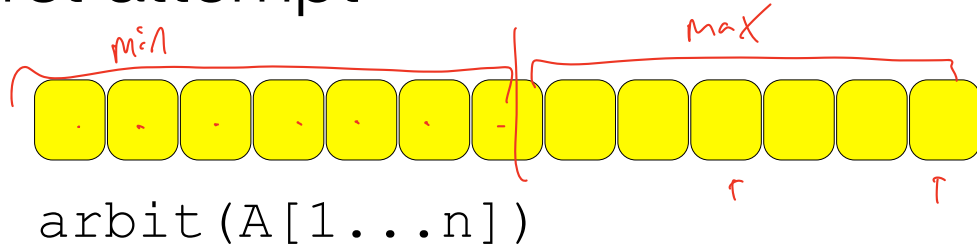
Main idea



Find the best arbitrage opportunity in LEFT and in RIGHT.

Then look for opportunities when you buy on the left and sell on the right.

first attempt



if $|A| = 2$, then base case

else

$lg \leftarrow \text{arbit}(A[1 \dots \lfloor n/2 \rfloor])$

$\rightarrow rg \leftarrow \text{arbit}(A[\lfloor n/2 \rfloor + 1, \dots, n])$

$\cdot \text{min}, \text{max} \leftarrow \text{MIN}(\underline{\text{left}}(A)), \text{MAX}(\text{right}(A))$

return $\max \{ lg, rg, \text{max} - \text{min} \}$

first attempt

arbit(A[1...n])

base case if $|A| \leq 2$

lg = arbit(left(A))

rg = arbit(right(A))

→ minl = min(left(A))

maxr = max(right(A))

return max{maxr-minl, lg, rg}

$\min = \infty$
for $i=1, n/2$
if $A[i] < \min_1$
 $\min = A[i]$

return $(A_2 - A_1)$.

$T(n/2)$

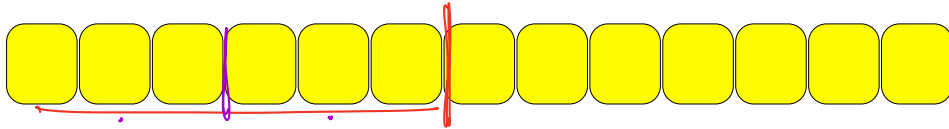
$T(n/2)$

$\Theta(n)$

case 2

$$T(n) = \underline{2T\left(\frac{n}{2}\right)} + \underline{\Theta(n)} \Rightarrow \underline{\underline{\Theta(n \log n)}}$$

first attempt: time $\Theta(n \log n)$



arbit(A[1...n])

base case if $|A| \leq 2$ |

lg = arbit(left(A)) $T(n/2)$

rg = arbit(right(A)) $T(n/2)$

minl = min(left(A))
maxr = max(right(A))

which takes $\Theta(n)$

return max{maxr-minl, lg, rg} |

better approach

$$T(n) = 2T\left(\frac{n}{2}\right) + \Theta(n) \leftarrow \text{can this be reduced?}$$

better approach

Can we find a solution that has $T(n) = 2T(n/2) + \underline{O(1)}$?

if we could, then the solution would be

case I

$$\Theta(n^{\log_2 2}) = \Theta(n)$$

better approach

Can we find a solution that has $T(n) = 2T(n/2) + O(1)$?

```
minl = min(left(A))
```

```
maxr = max(right(A))
```

```
return max{maxr-minl, lg, rg}
```

→ Have arbit function ALSO return min, max of
the array

second attempt

arbit+(A[1...n])

base case if $|A| \leq 2$

$lg, \underline{lmin}, \underline{lmax} \leftarrow \text{arbit+}(\text{left}(A))$ $T(\frac{n}{2})$

$rg, \underline{rmin}, \underline{rmax} \leftarrow \text{arbit+}(\text{right}(A))$ $T(\frac{n}{2})$

$\rightarrow \text{mid} = \underline{rmax} - \underline{lmin}$ I

return $\max \{ lg, rg, \text{mid} \}$, I

$\cdot \min \{ lmin, rmin \}$, I

$\max \{ lmax, rmax \}$ I

second attempt

arbit+(A[1...n])

base case if $|A| \leq 2$, *if $|A|=1, \{0, A_1, A_1\}$* return $A_2 - A_1, \min(A_1, A_2), \max(A_1, A_2)$

(lg, minl, maxl) = arbit(left(A))

(rg, minr, maxr) = arbit(right(A))

return $\max\{\maxr - \minl, \lg, rg\},$
 $\min\{\minl, \minr\},$
 $\max\{\maxl, \maxr\}$

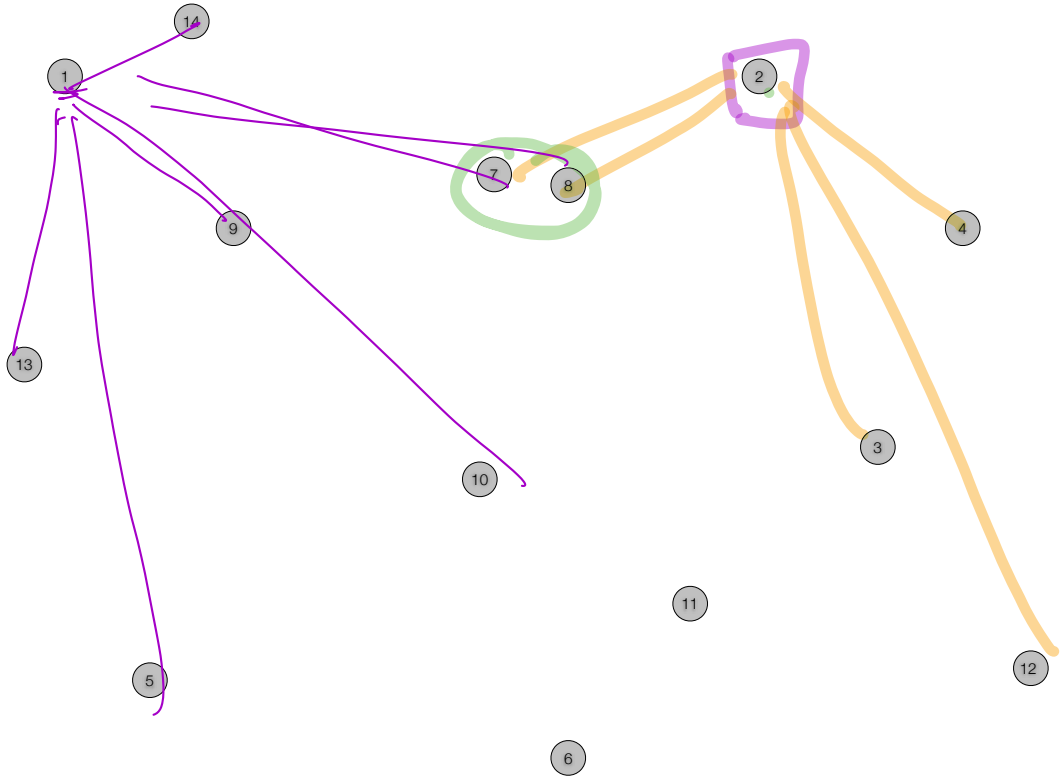
$$T(n) = 2T\left(\frac{n}{2}\right) + \Theta(1) \Rightarrow T(n) = \Theta(n) \text{ by case I.}$$

closest pair

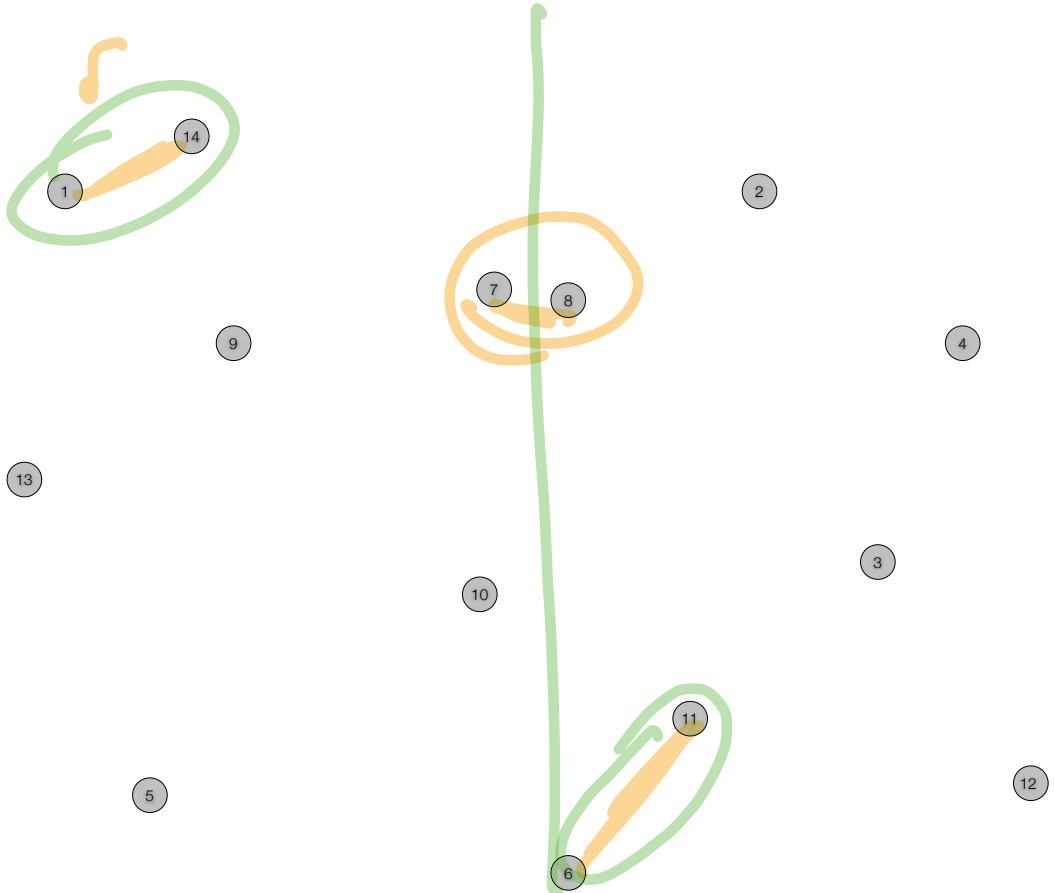
of points



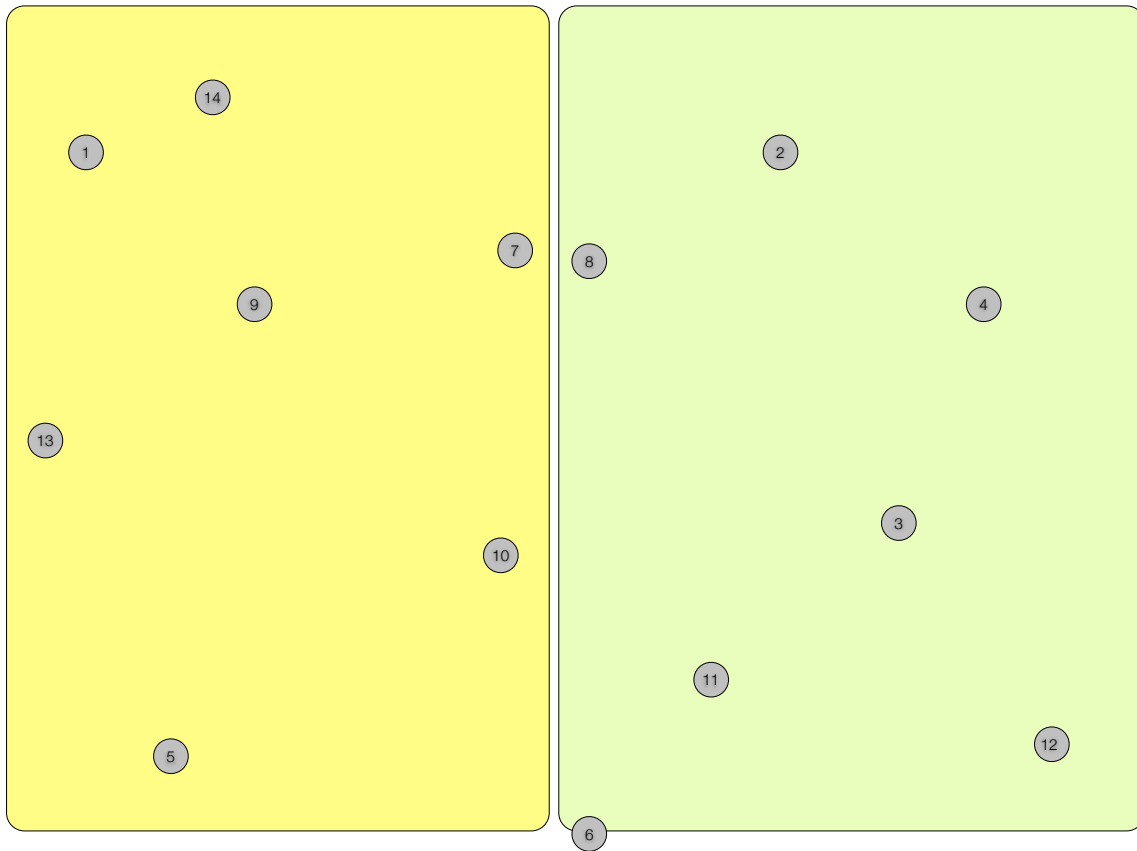
Simple brute force approach takes $\Theta(n^2)$



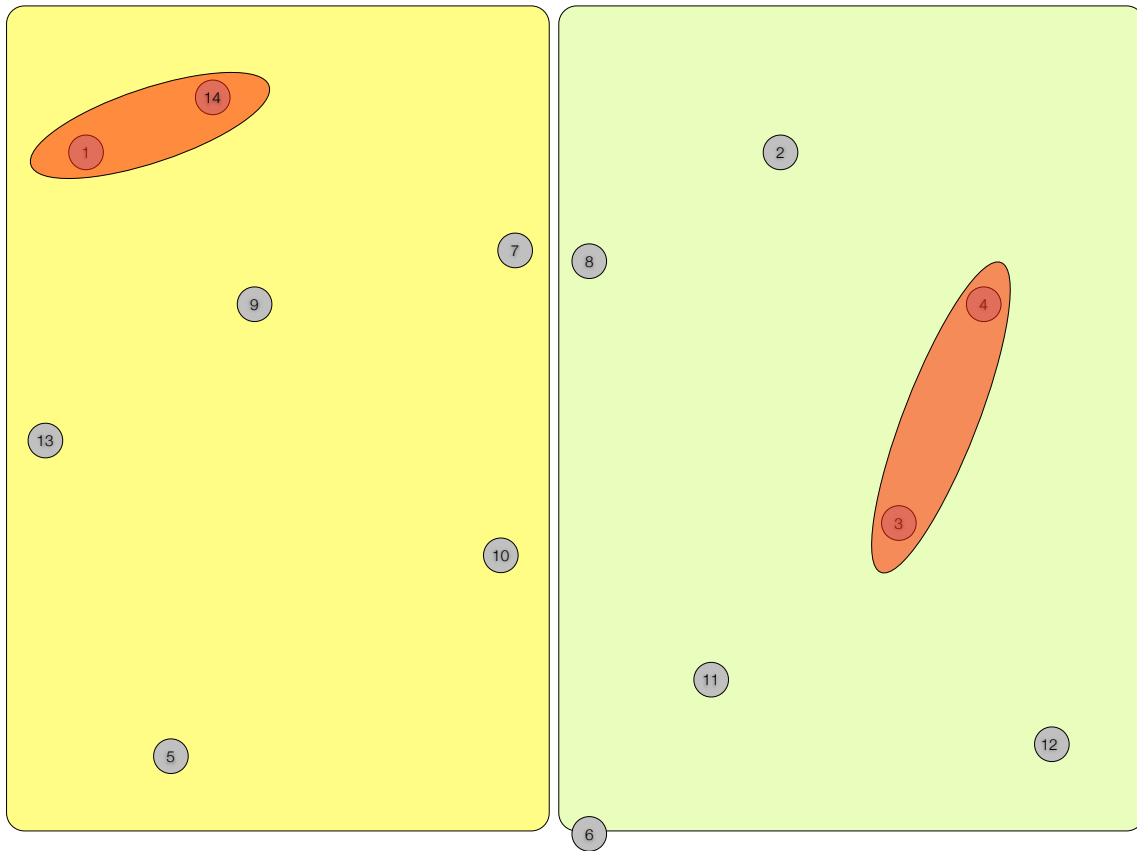
solve the large problem by
solving smaller problems
and combining solutions



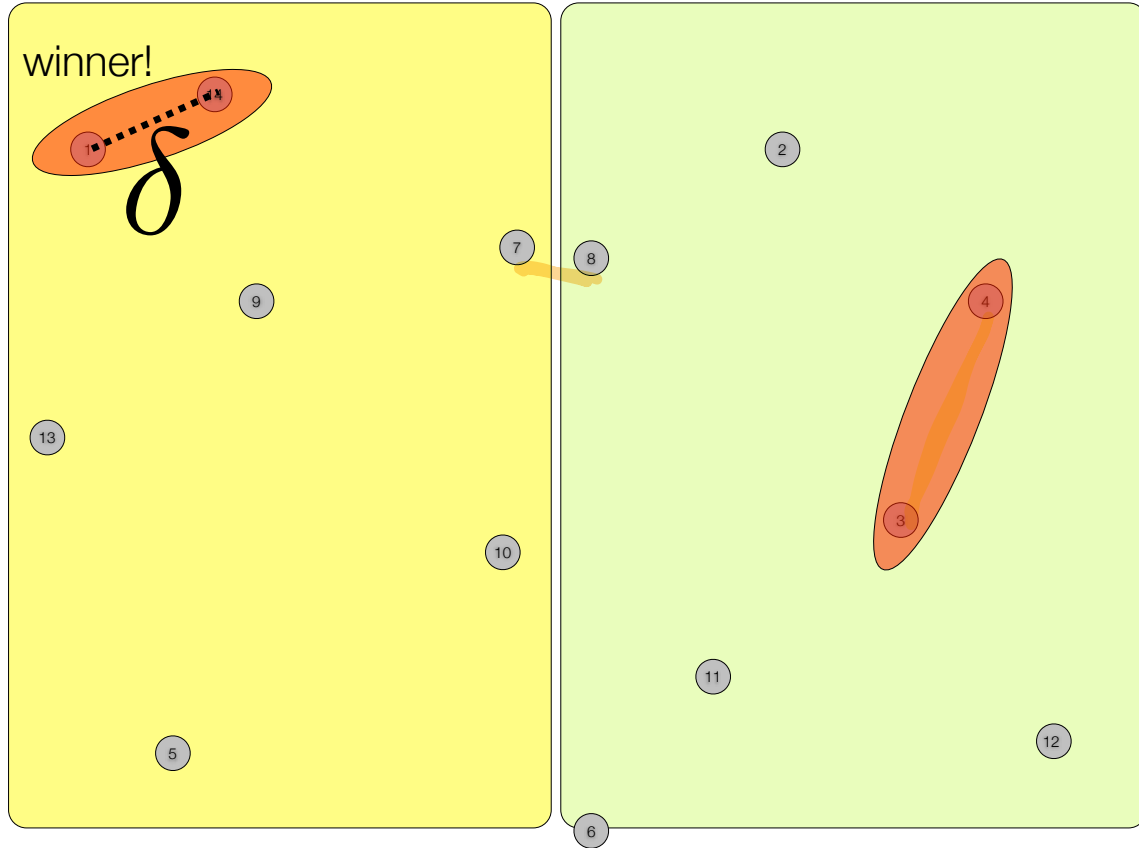
Divide & Conquer



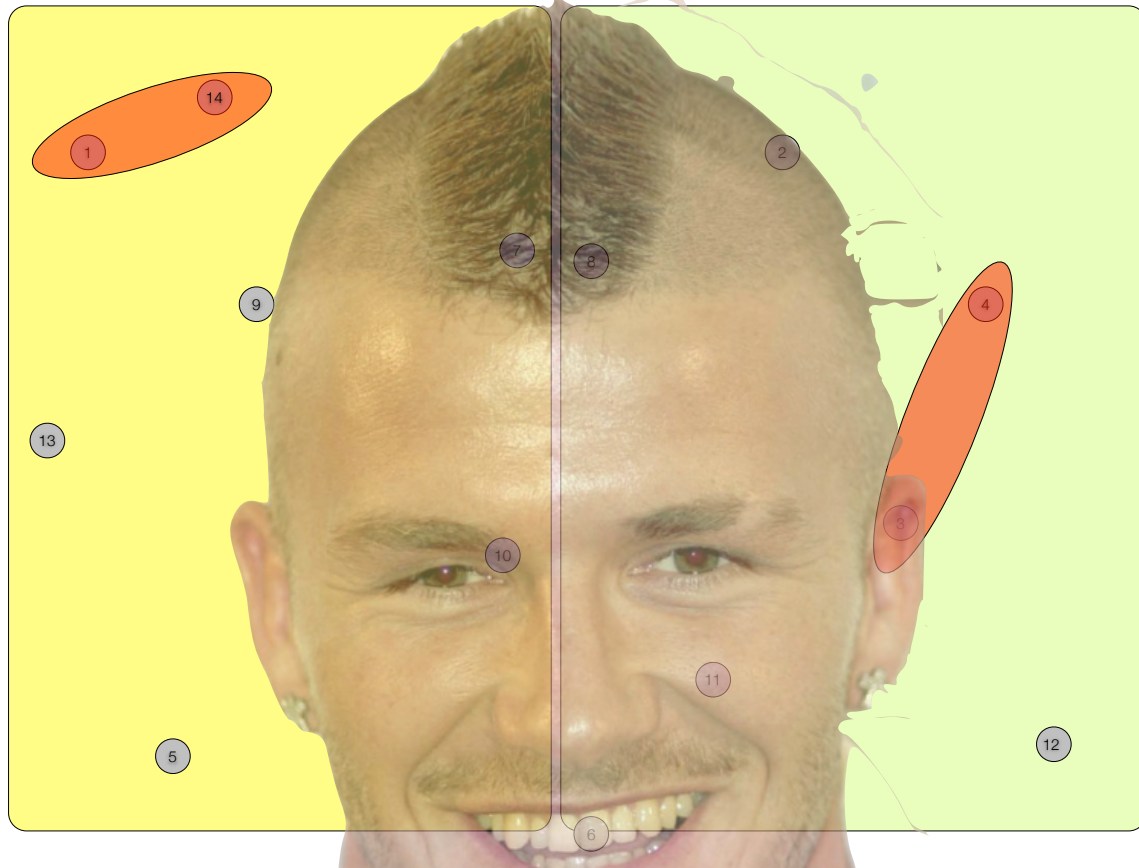
Divide & Conquer



Divide & Conquer



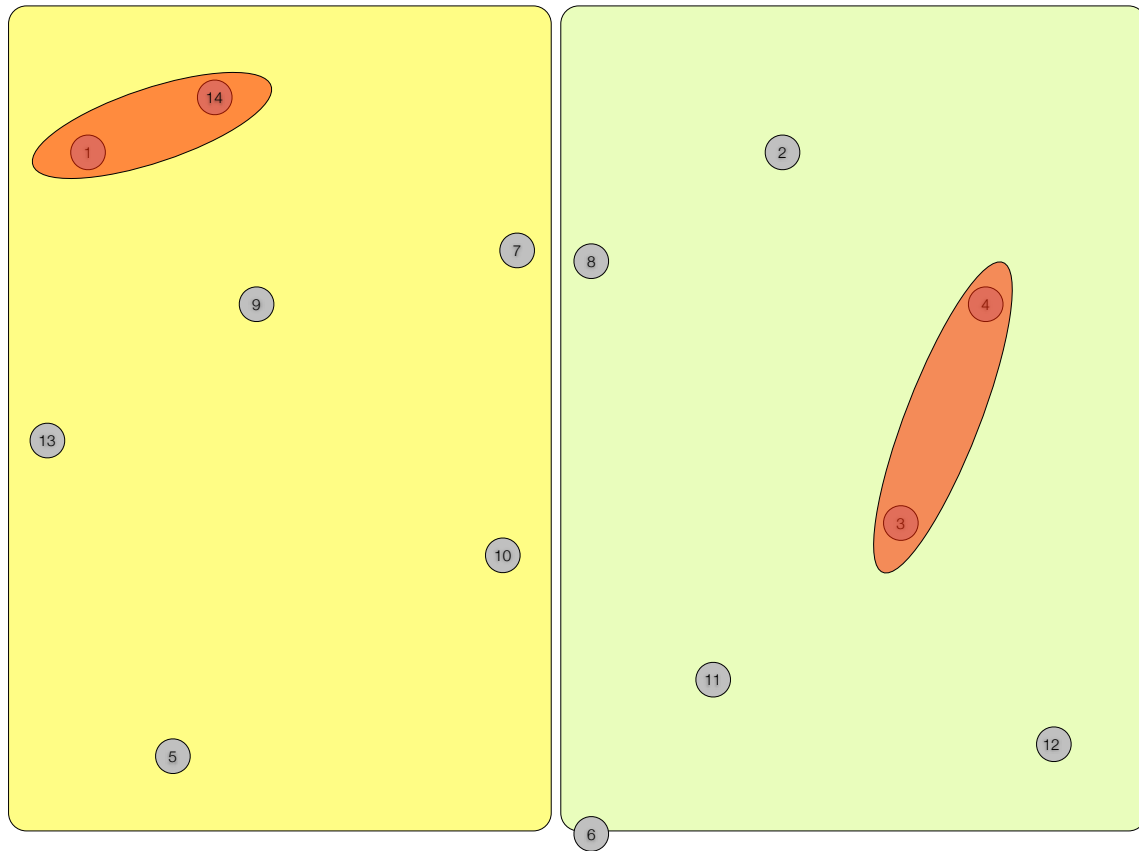
Divide & Conquer



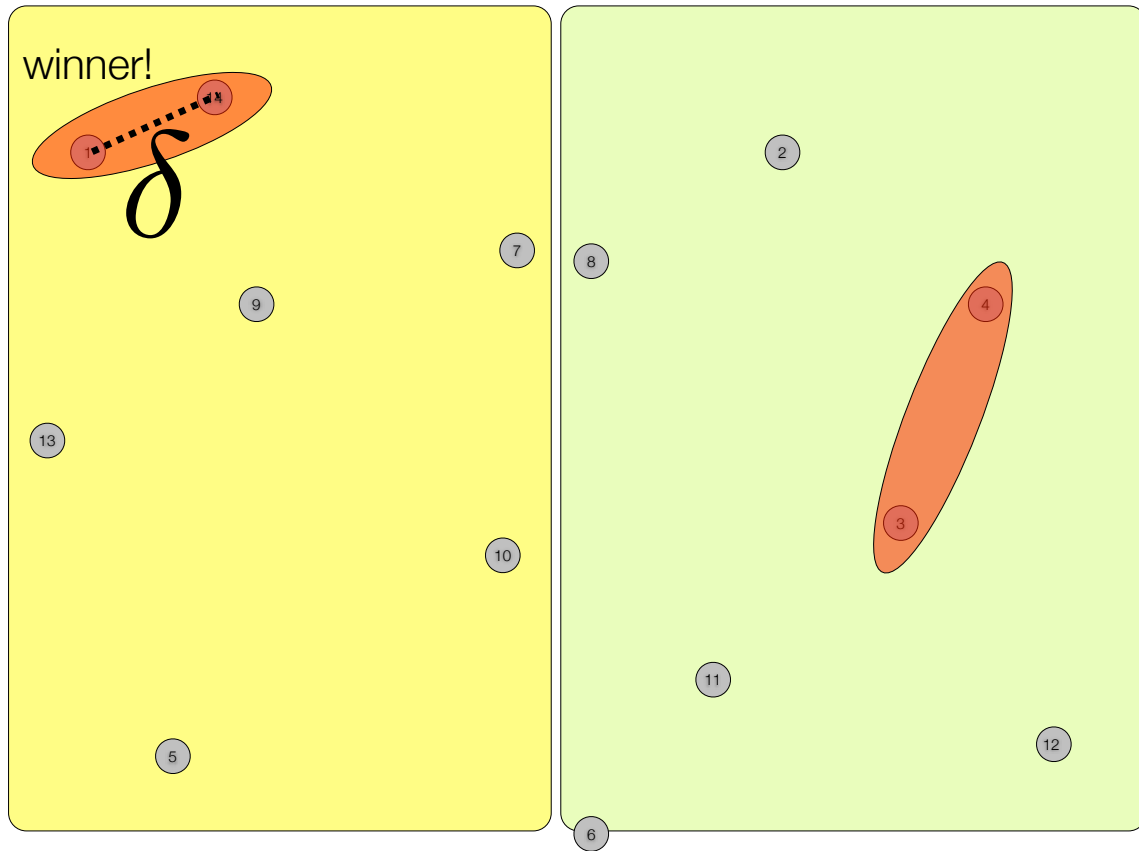
Divide & Conquer



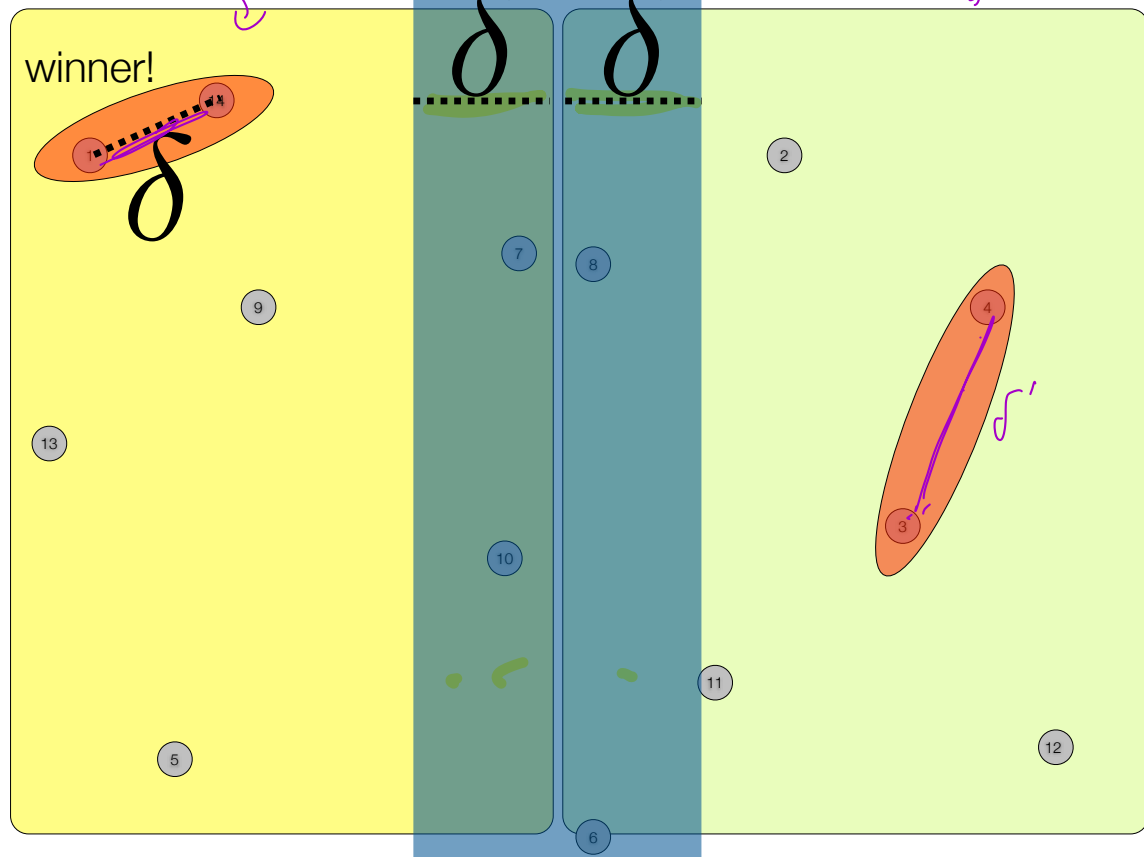
Divide & Conquer



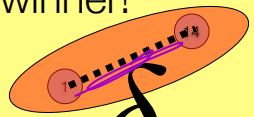
Divide & Conquer



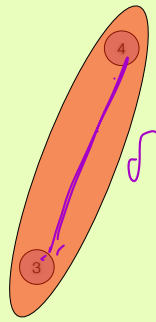
Divide & Conquer



winner!

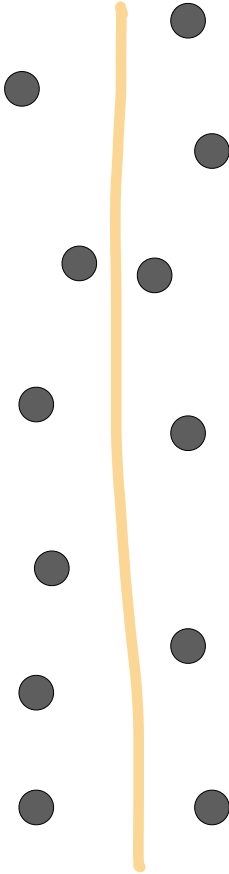


σ

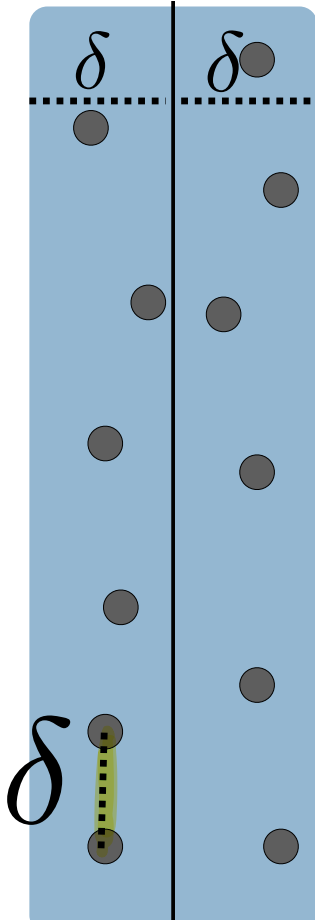


σ

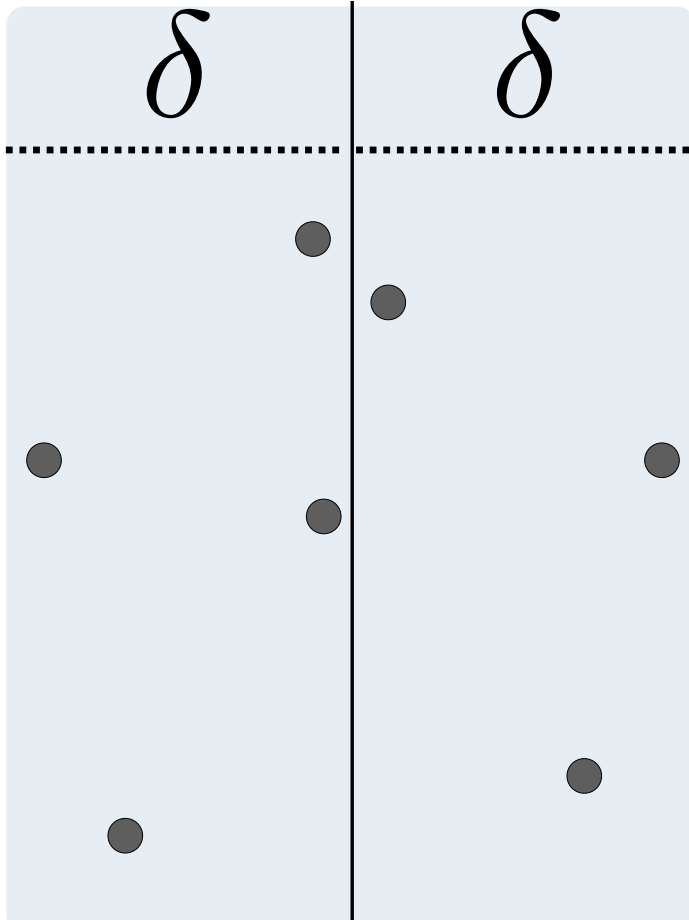
What if the input
points are
distributed like
this?



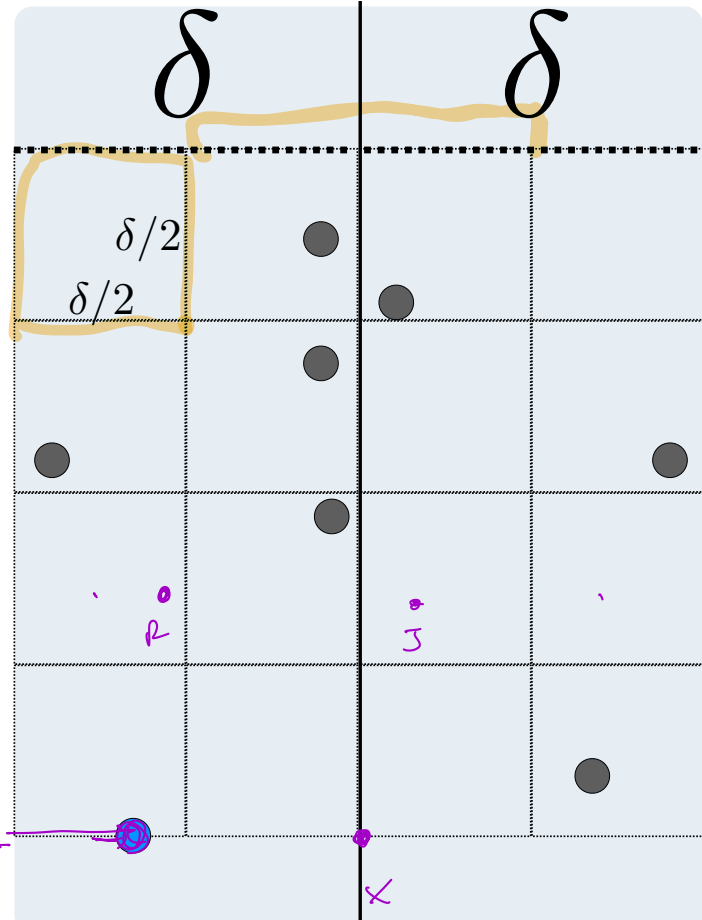
Then all of the points are within δ of the middle. If we need to check all of the points, we are back to $O(n^2)$

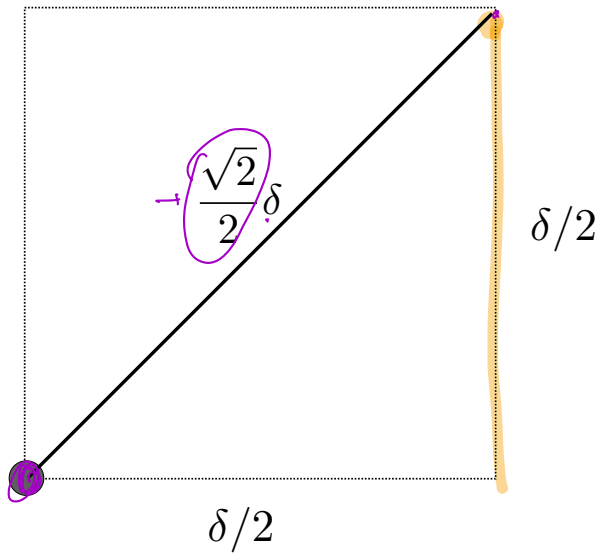


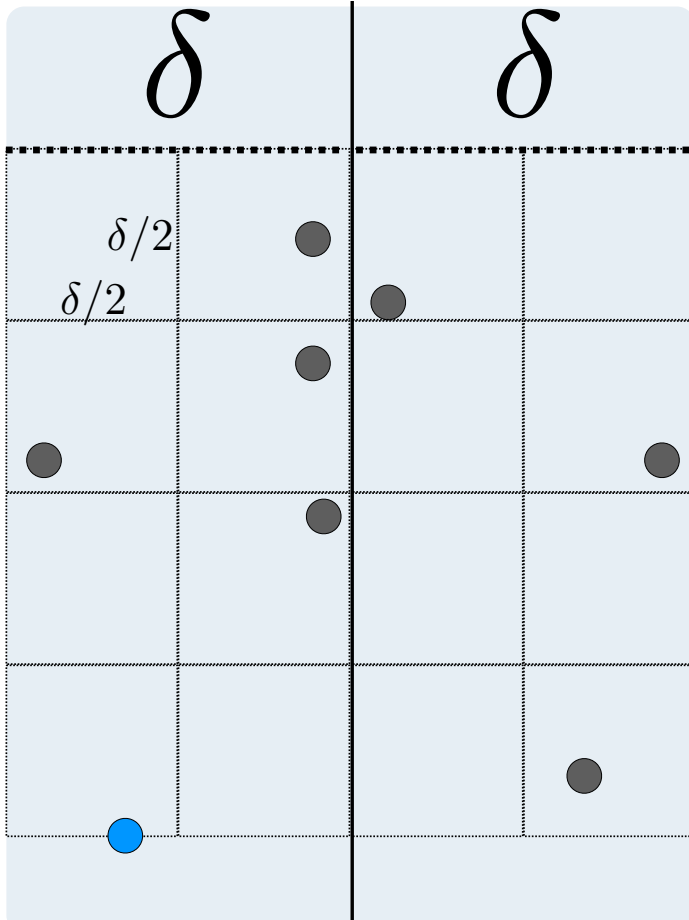
But we have extra information! The only candidates for closest pair are within δ of each other. How can we use this info?



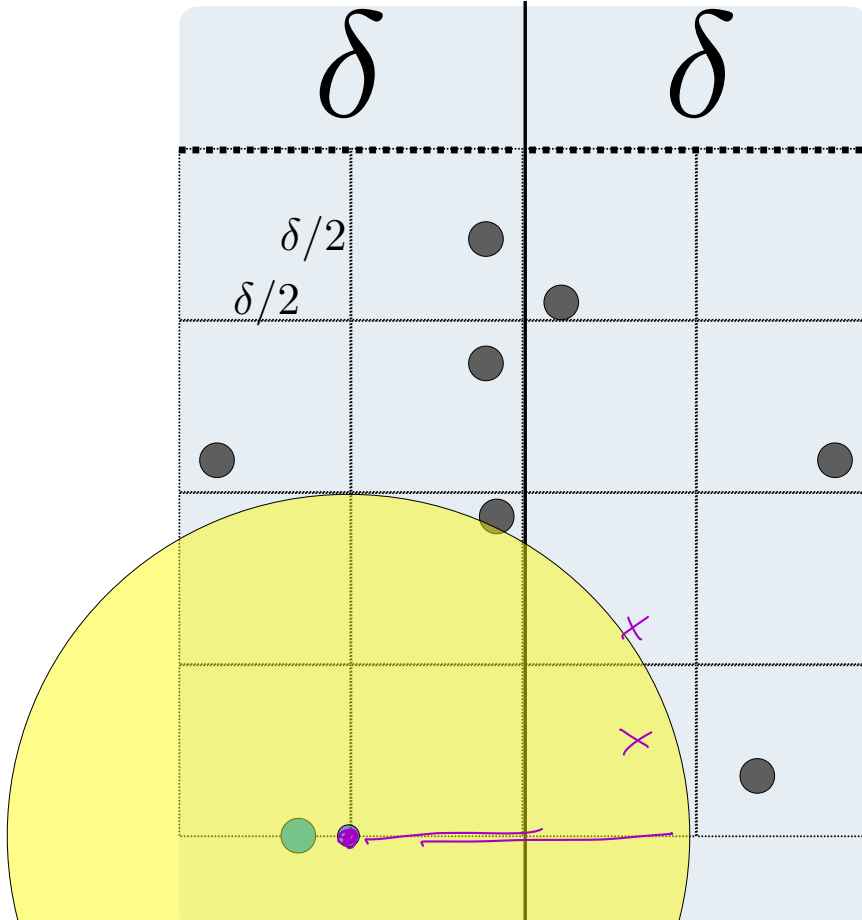
Imagine
there is
a grid of
cubbies
starting at
the lowest
Y point



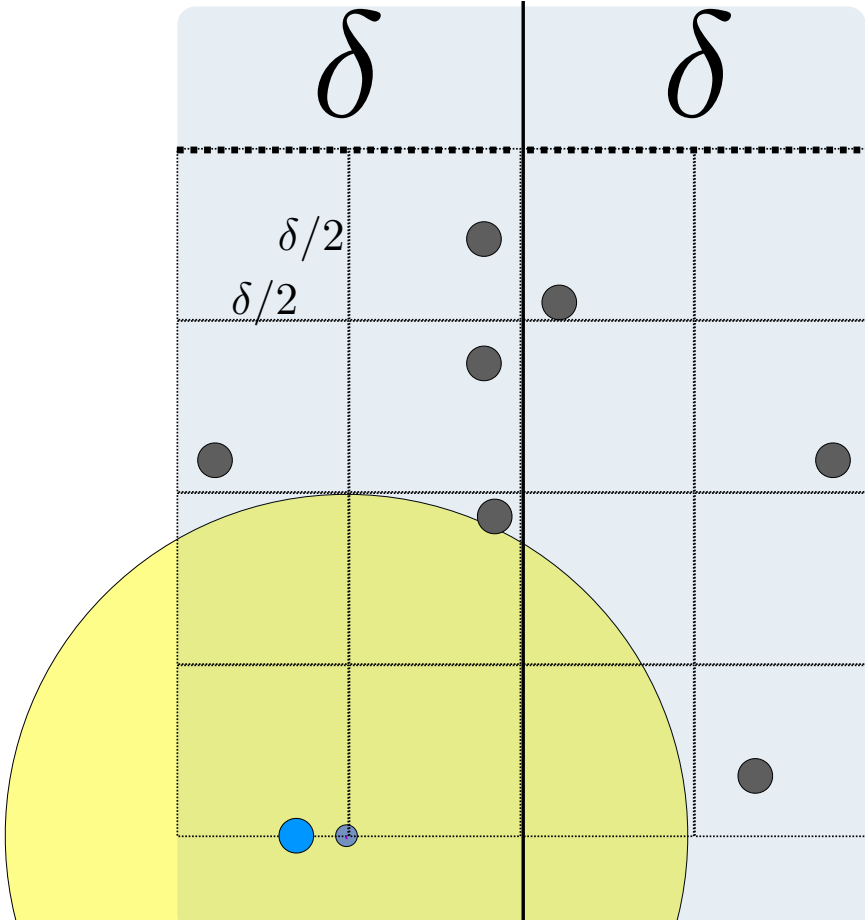




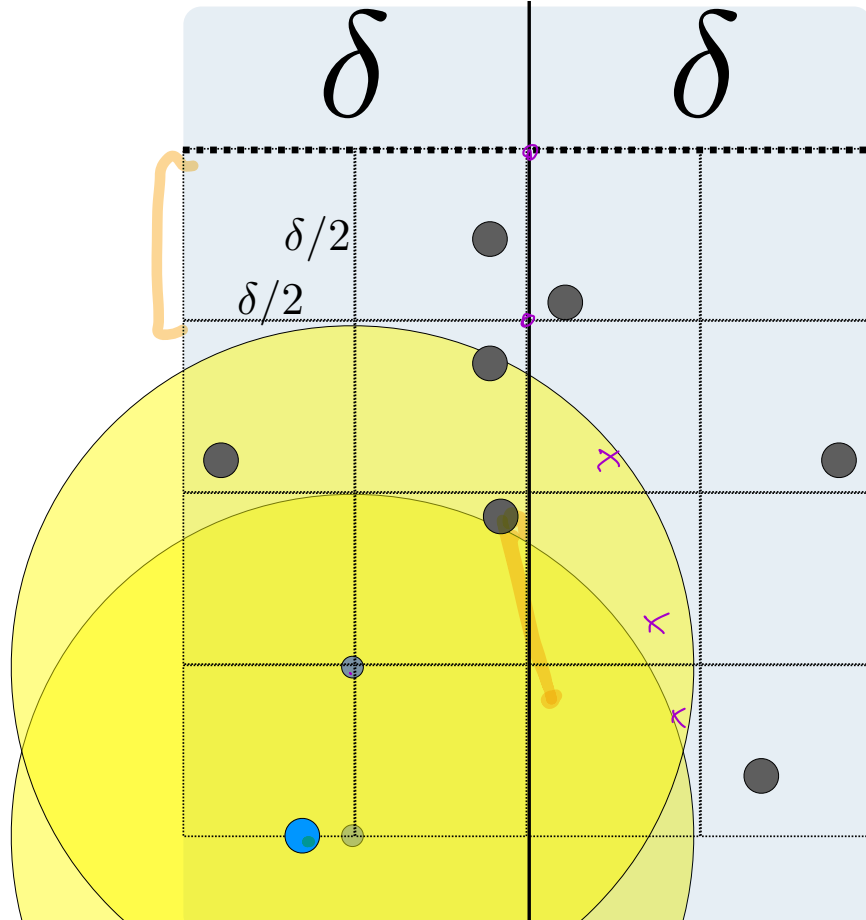
FACT: At most 1 point in each cubby



FACT: ≤ 1
point per
cubby

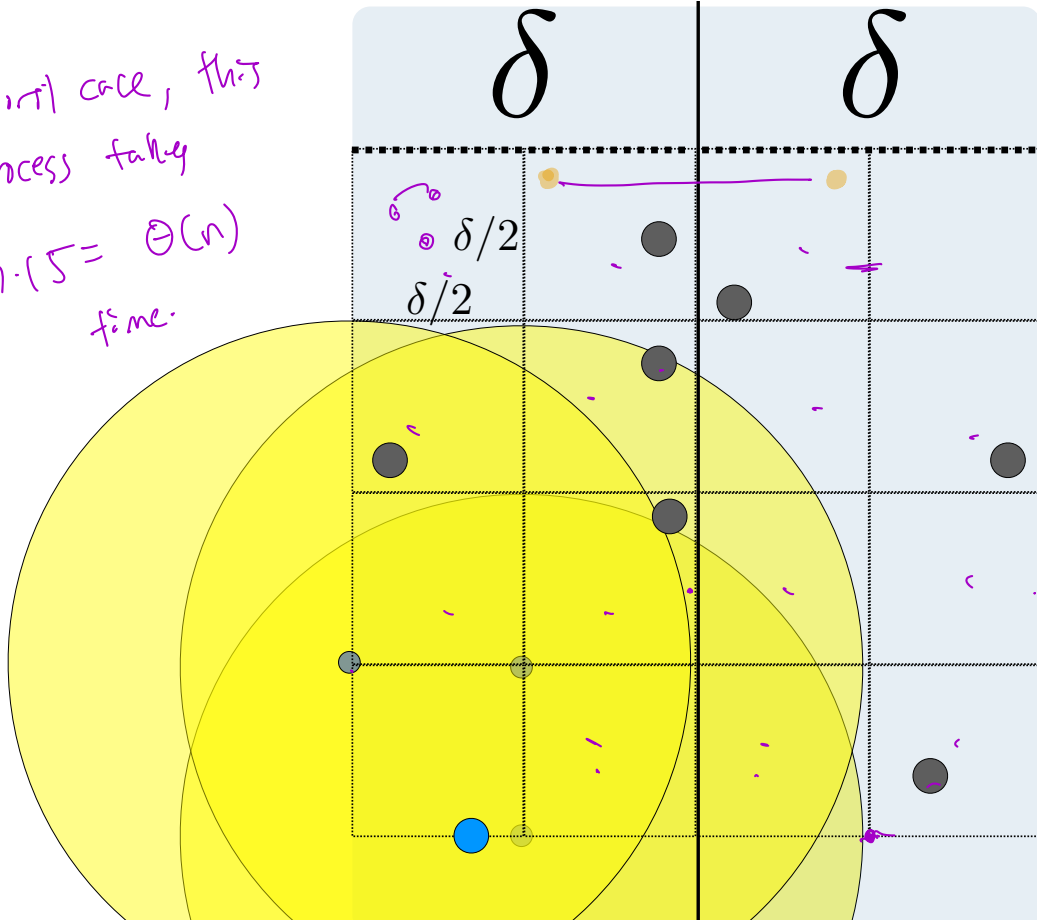


FACT: ≤ 1
point per
cubby



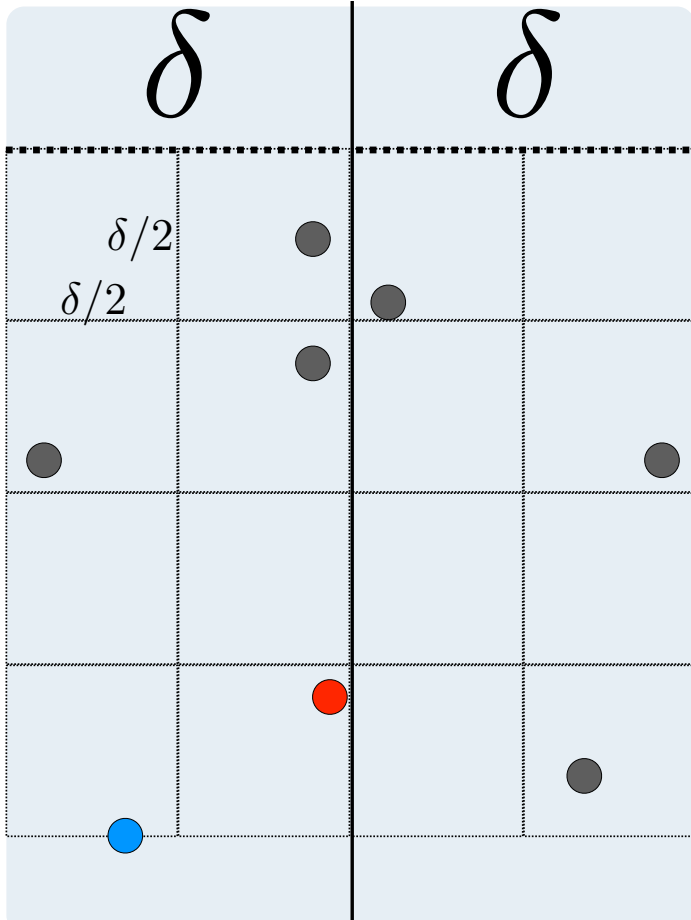
FACT: ≤ 1
point per
cubby

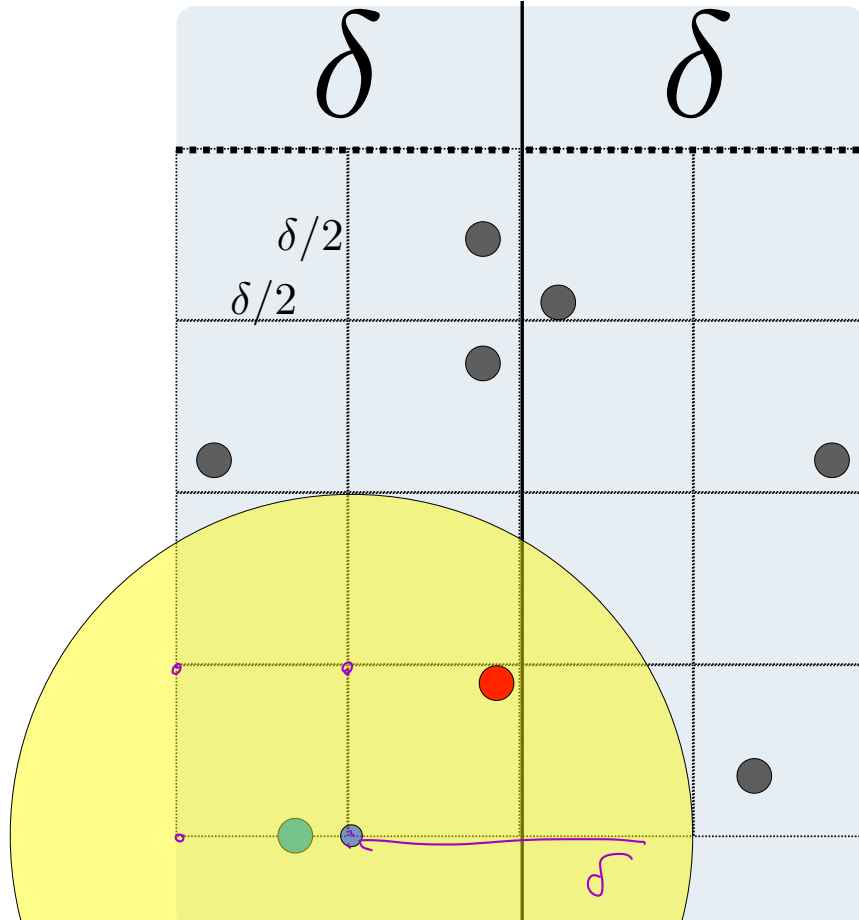
Worst case, this
 process takes
 $n \cdot 15 = \Theta(n)$
 time.

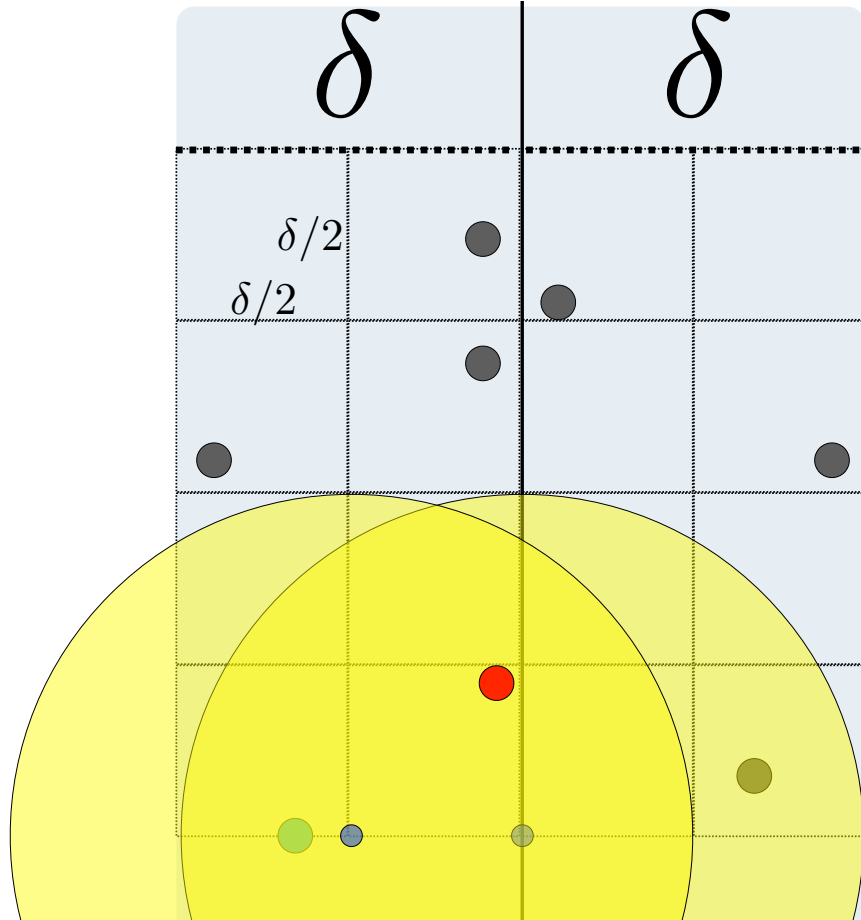


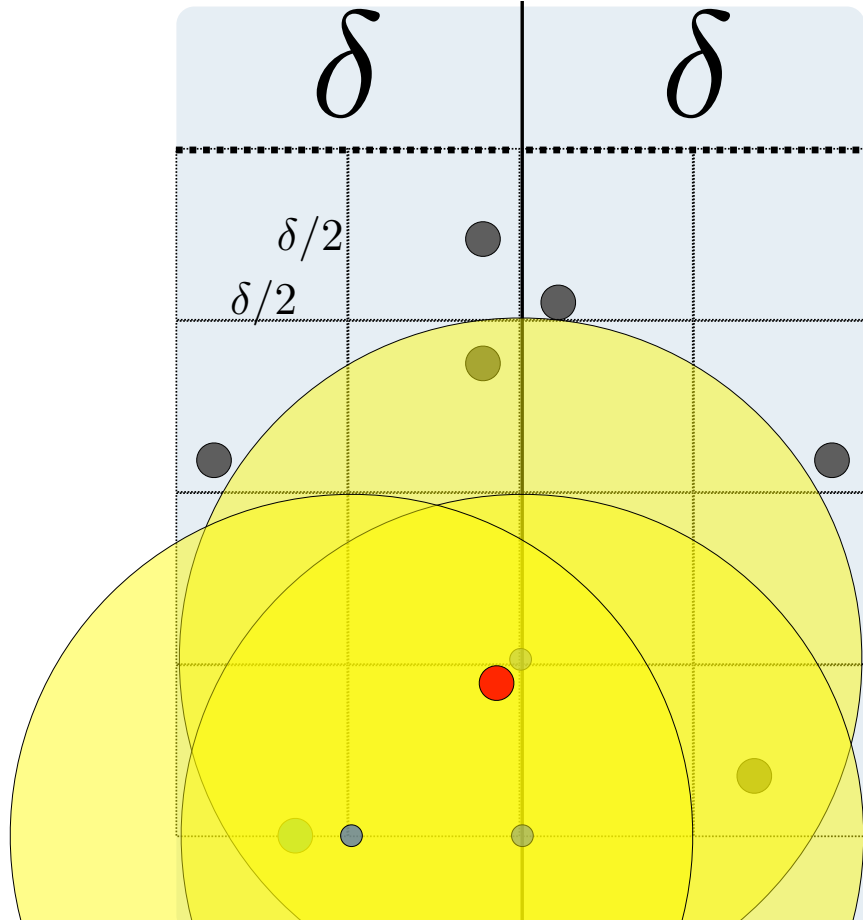
FACT: ≤ 1
 point per
 cubby

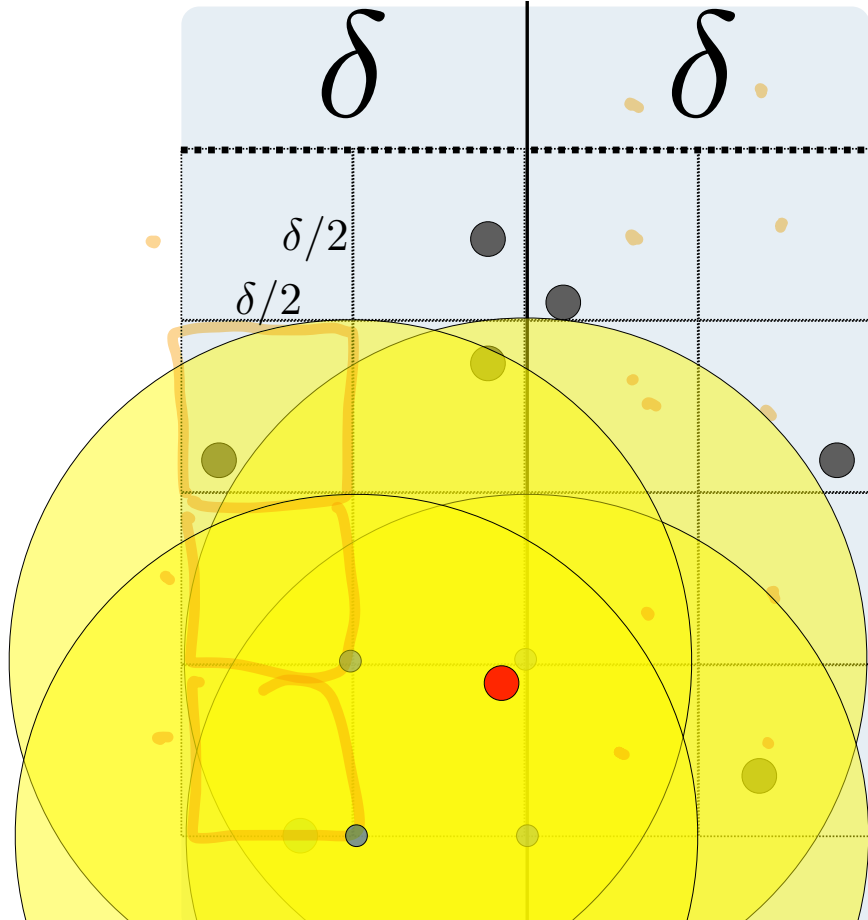
15 cubbies in
 which
 Romeo can
 find
 Juliet.

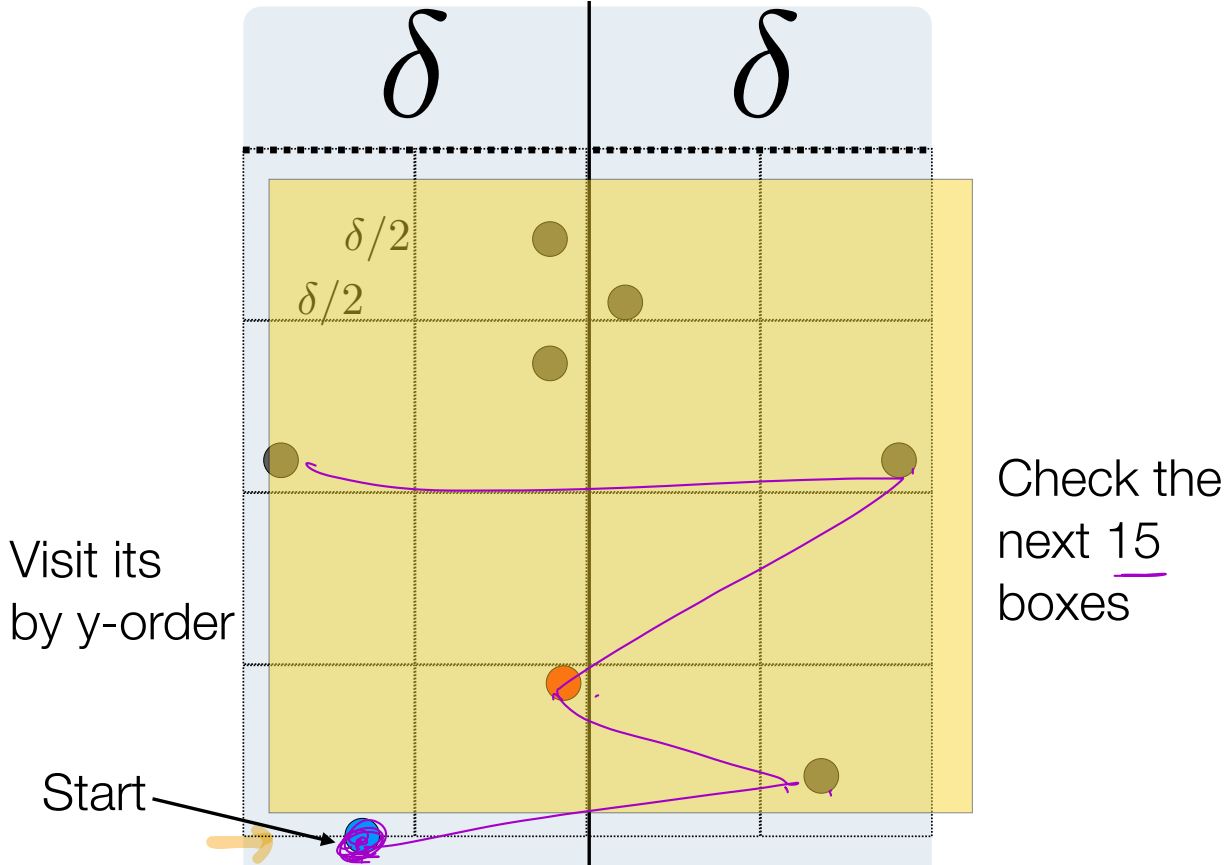


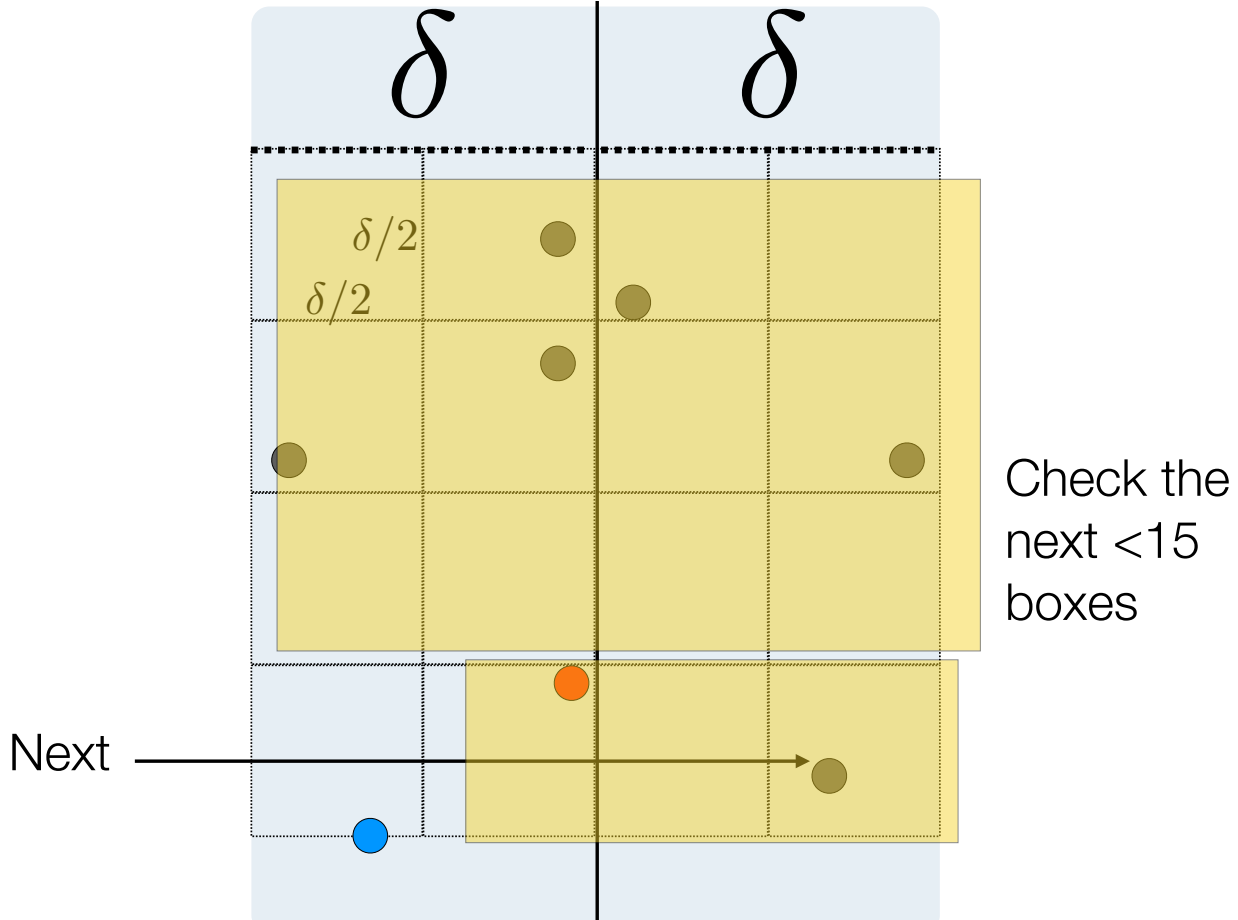


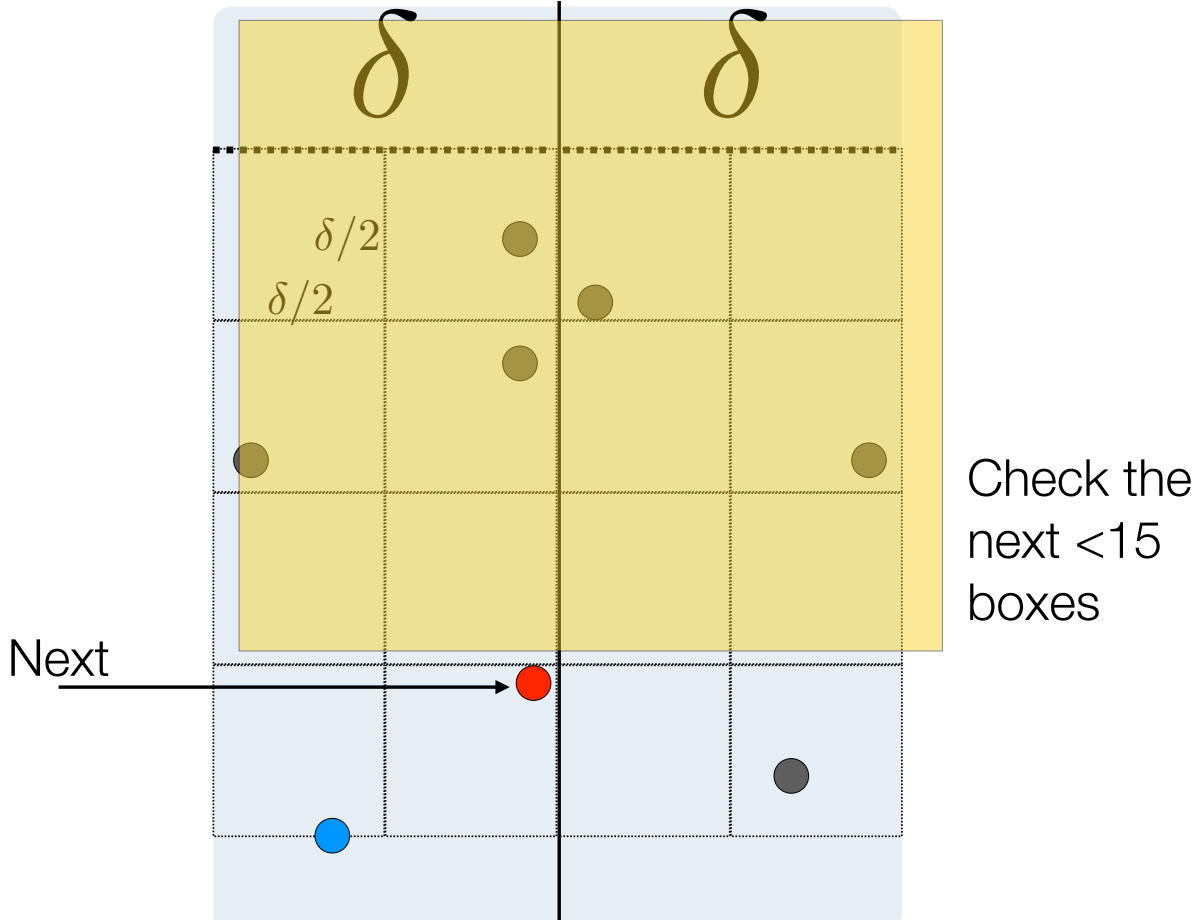












Closest(P)

)

Closest(P)

Base Case: If < 8 points, brute force.

1. Let q be the “middle-element” of points

2. Divide P into Left, Right according to q

3. $\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}), \text{Closest}(\text{Right}))$

4. Mohawk = { Scan P , add pts that are delta from $q.x$ }

5. For each point x in Mohawk (in y-order):

 Compute distance to its next 15 neighbors

 Update delta, r, j if any pair (x, y) is $< \text{delta}$

6. Return (delta, r, j)

Closest(P)

Base Case: If < 8 points, brute force.

1. Let q be the “middle-element” of points ✓

2. Divide P into Left, Right according to q

3. $\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}), \text{Closest}(\text{Right}))$

4. Mohawk = { Scan P , add pts that are delta from $q.x$ }

5. For each point x in Mohawk (in y -order): ✓

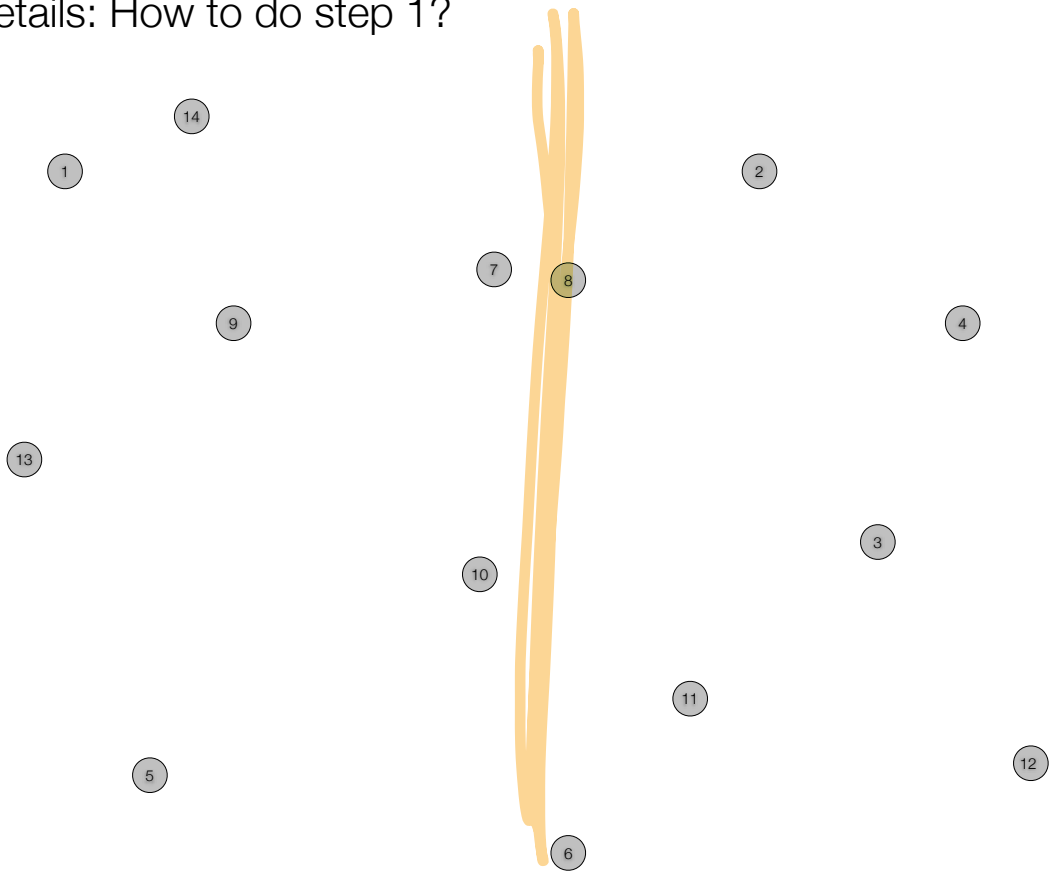
 Compute distance to its next 15 neighbors

 Update delta, r, j if any pair (x, y) is $< \text{delta}$

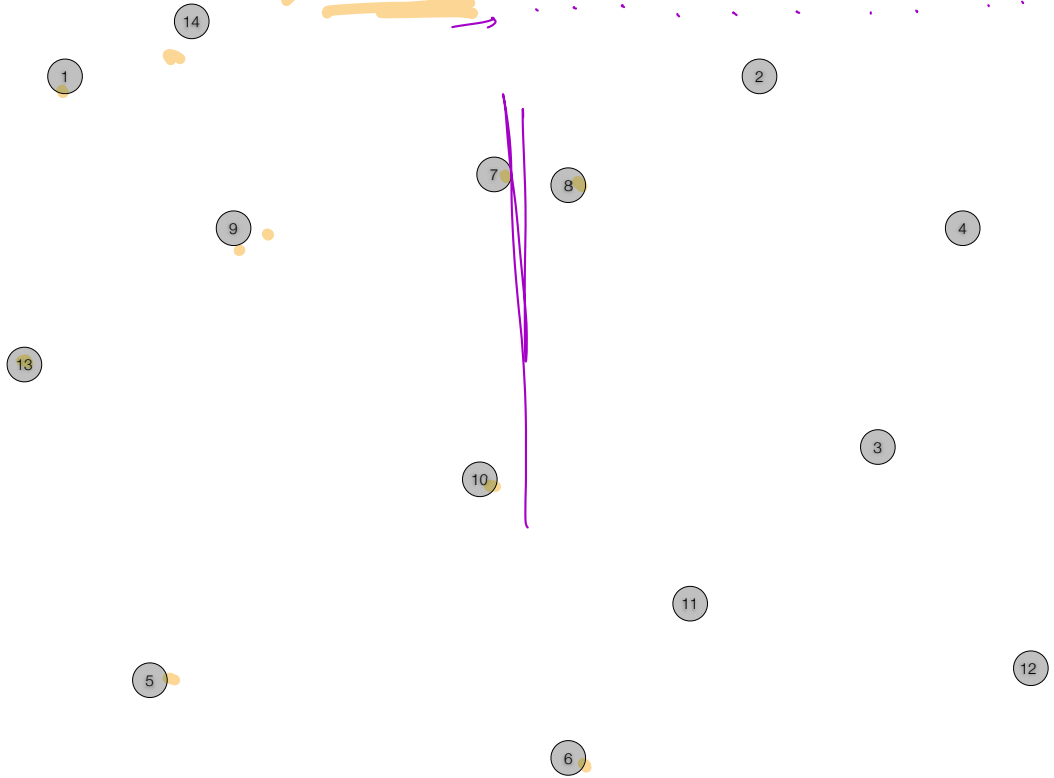
6. Return (delta, r, j)

Can be reduced to 7!

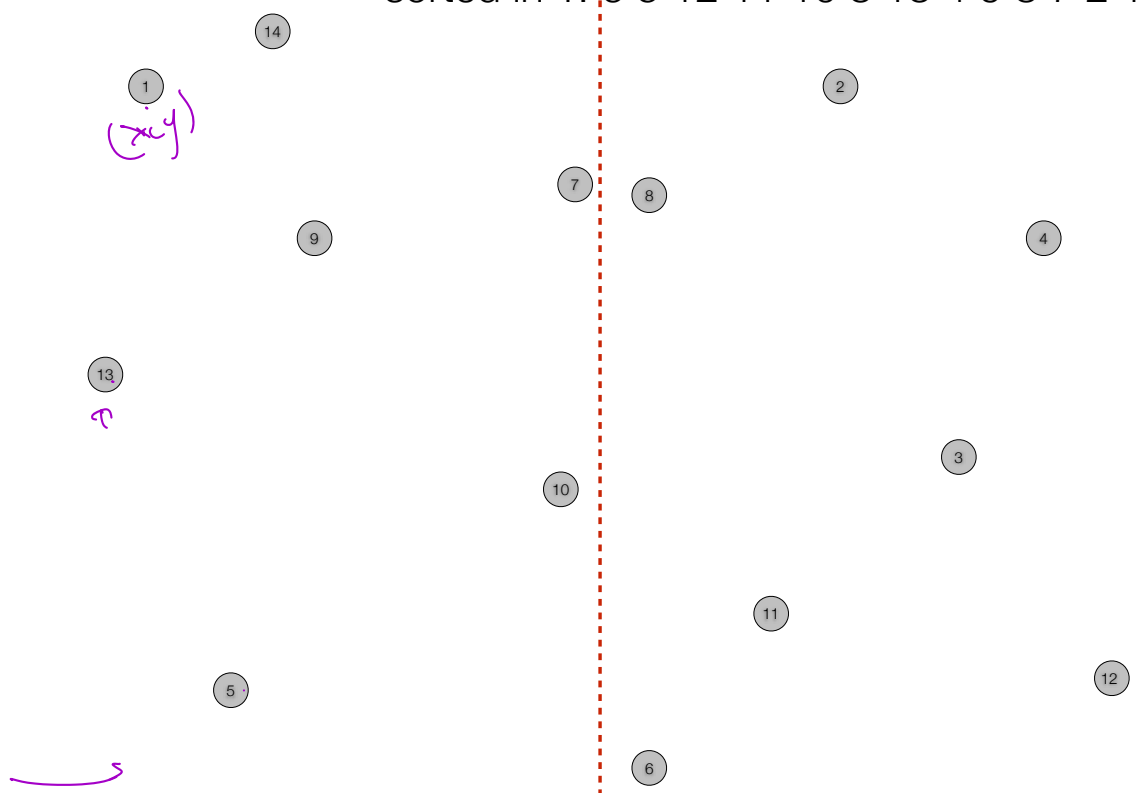
Details: How to do step 1?



sorted in X: 13 1 5 14 9 10 7 | 9 8 11 2 3 4 12
sorted in Y: 6 5 12 11 10 3 13 4 9 8 7 2 1 14



sorted in X: 13 1 5 14 9 10 7 9 8 11 2 3 4 12 →
sorted in Y: 6 5 12 11 10 3 13 4 9 8 7 2 1 14 ↑



ClosestPair(P)

Compute Sorted-in-X list SX

$\Theta(n \cdot \log n)$

Compute Sorted-in-Y list SY

$\Theta(n \cdot \log n)$

Closest(P, SX, SY) T(n) =

$\Theta(n \cdot \log n)$

Total = $\Theta(n \cdot \log n)$

Closest(P, SX, SY) *sorted list*

Let q be the middle-element of SX *points* ①

Divide P into Left, Right according to q ①

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, \text{LX}, \text{LY}), \text{Closest}(\text{Right}, \text{RX}, \text{RY}))$

Mohawk = { Scan SY, add pts that are delta from q.x } $2T(\frac{n}{2})$
 $\Theta(n)$

For each point x in Mohawk (in order):

Compute distance to its next 15 neighbors

Update delta, r, j if any pair (x, y) is < delta

} $\Theta(n)$

Return (delta, r, j)

$$T(n) = 2T(\frac{n}{2}) + \Theta(n) \Rightarrow \Theta(n \log n)$$

Closest(P, SX, SY)

Let q be the middle-element of SX

Divide P into Left, Right according to q

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, LX, LY) \quad \text{Closest}(\text{Right}, RX, RY))$

Mohawk = { Scan SY , add pts that are delta from $q.x$ }

For each point x in Mohawk (in order):

 Compute distance to its next 15 neighbors

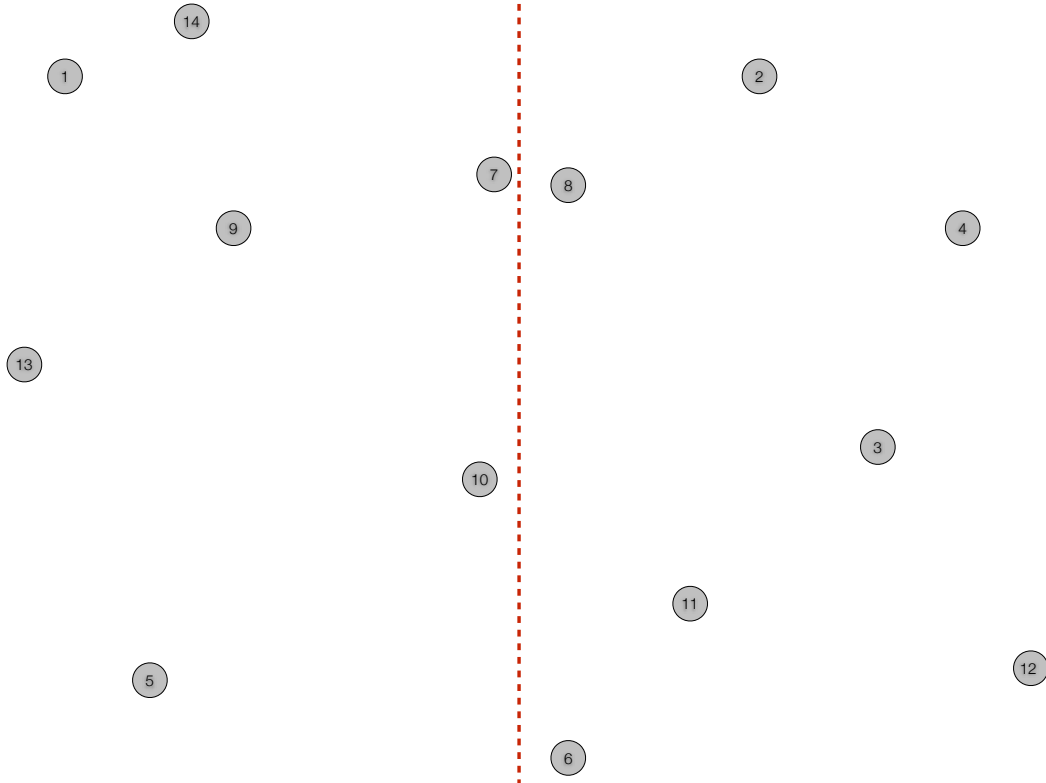
 Update delta, r, j if any pair (x, y) is $< \text{delta}$

Return (delta, r, j)

Can be reduced to 7!



sorted in X: 13 1 5 14 9 10 7 9 8 11 2 3 4 12
sorted in Y: 6 5 12 11 10 3 13 4 9 8 7 2 1 14



Closest(P, SX, SY)

Let q be the middle-element of SX

Divide P into Left, Right according to q. Scan to get LY, RY.

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, \text{LX}, \text{LY}), \text{Closest}(\text{Right}, \text{RX}, \text{RY}))$

Mohawk = { Scan SY, add pts that are delta from q.x }

For each point x in Mohawk (in order):

 Compute distance to its next 15 neighbors

 Update delta, r, j if any pair (x, y) is < delta

Return (delta, r, j)

Closest(P, SX, SY)

Let q be the middle-element of SX

Divide P into Left, Right according to q. Scan to get LY, RY.

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, \text{LX}, \text{LY}) \quad \text{Closest}(\text{Right}, \text{RX}, \text{RY}))$

Mohawk = { Scan SY, add pts that are delta from q.x }

For each point x in Mohawk (in order):

 Compute distance to its next 15 neighbors

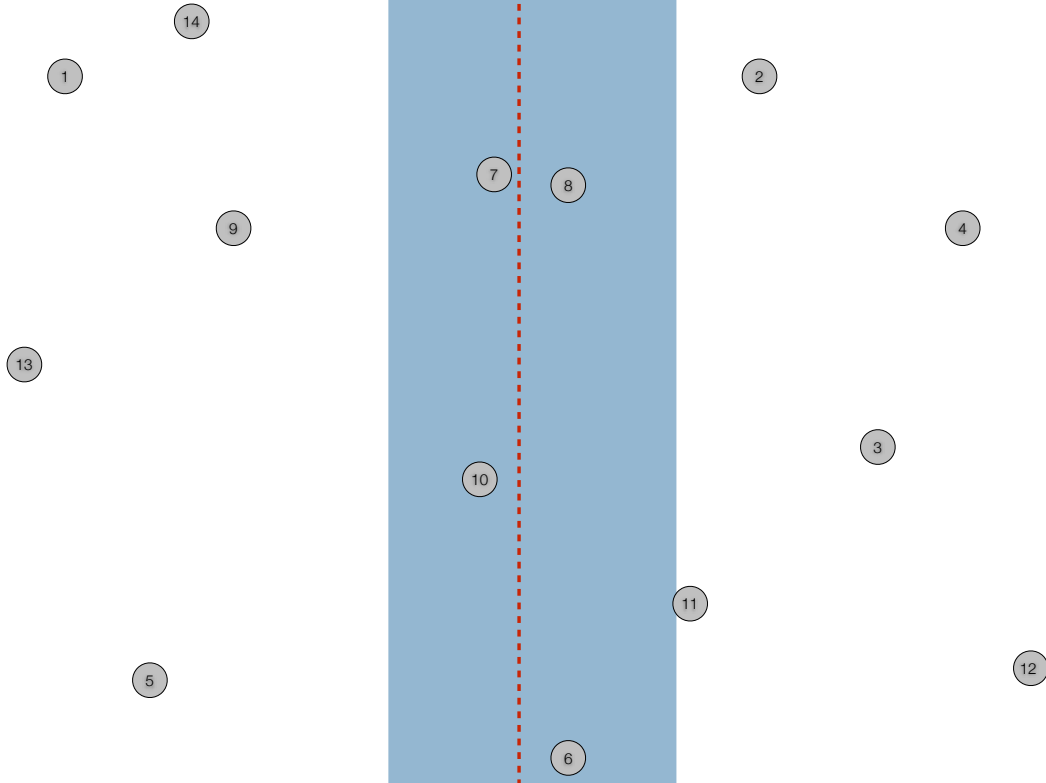
 Update delta, r, j if any pair (x, y) is < delta

Return (delta, r, j)

Can be reduced to 7!



sorted in X: 13 1 5 14 9 10 7 9 8 11 2 3 4 12
sorted in Y: 6 5 12 11 10 3 13 4 9 8 7 2 1 14



Closest(P, SX, SY)

Let q be the middle-element of SX

Divide P into Left, Right according to q. Scan to get LY, RY.

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, \text{LX}, \text{LY}), \text{Closest}(\text{Right}, \text{RX}, \text{RY}))$

Mohawk = { Scan SY, add pts that are delta from q.x }

For each point x in Mohawk (in order):

 Compute distance to its next 15 neighbors

 Update delta, r, j if any pair (x, y) is < delta

Return (delta, r, j)

Closest(P, SX, SY)

Let q be the middle-element of SX

Divide P into Left, Right according to q. Scan to get LY, RY.

$\text{delta}, r, j = \text{MIN}(\text{Closest}(\text{Left}, \text{LX}, \text{LY}) \quad \text{Closest}(\text{Right}, \text{RX}, \text{RY}))$

Mohawk = { Scan SY, add pts that are delta from q.x }

For each point x in Mohawk (in order):

 Compute distance to its next 15 neighbors

 Update delta, r, j if any pair (x, y) is < delta

Return (delta, r, j)

Can be reduced to 7!



Running time for Closest pair algorithm

$$T(n) =$$

$$T(n) = 2T(n/2) + \Theta(n) = \Theta(n \log n)$$

@author Robert Sedgwick
@author Kevin Wayne

<http://algs4.cs.princeton.edu/99hull/ClosestPair.java.html>

```
public ClosestPair(Point2D[] points) {
    int N = points.length;
    if (N <= 1) return;

    // sort by x-coordinate (breaking ties by y-coordinate)
    Point2D[] pointsByX = new Point2D[N];
    for (int i = 0; i < N; i++)
        pointsByX[i] = points[i];
    Arrays.sort(pointsByX, Point2D.X_ORDER);

    // check for coincident points
    for (int i = 0; i < N-1; i++) {
        if (pointsByX[i].equals(pointsByX[i+1])) {
            bestDistance = 0.0;
            best1 = pointsByX[i];
            best2 = pointsByX[i+1];
            return;
        }
    }

    // sort by y-coordinate (but not yet sorted)
    Point2D[] pointsByY = new Point2D[N];
    for (int i = 0; i < N; i++)
        pointsByY[i] = pointsByX[i];

    // auxiliary array
    Point2D[] aux = new Point2D[N];

    closest(pointsByX, pointsByY, aux, 0, N-1);
}
```

```
// find closest pair of points in pointsByX[lo..hi]
// precondition: pointsByX[lo..hi] and pointsByY[lo..hi] are the same sequence of points, sorted by x,y-coord
private double closest(Point2D[] pointsByX, Point2D[] pointsByY, Point2D[] aux, int lo, int hi) {
    if (hi <= lo) return Double.POSITIVE_INFINITY;
```

```
    int mid = lo + (hi - lo) / 2;
    Point2D median = pointsByX[mid];
```

```
    // compute closest pair with both endpoints in left subarray or both in right subarray
    double delta1 = closest(pointsByX, pointsByY, aux, lo, mid);
    double delta2 = closest(pointsByX, pointsByY, aux, mid+1, hi);
    double delta = Math.min(delta1, delta2);
```

```
    // merge back so that pointsByY[lo..hi] are sorted by y-coordinate
    merge(pointsByY, aux, lo, mid, hi);
```

```
    // aux[0..M-1] = sequence of points closer than delta, sorted by y-coordinate
    int M = 0;
    for (int i = lo; i <= hi; i++) {
        if (Math.abs(pointsByY[i].x() - median.x()) < delta)
            aux[M++] = pointsByY[i];
    }
```

```
    // compare each point to its neighbors with y-coordinate closer than delta
    for (int i = 0; i < M; i++) {
        // a geometric packing argument shows that this loop iterates at most 7 times
        for (int j = i+1; (j < M) && (aux[j].y() - aux[i].y()) < delta; j++) {
            double distance = aux[i].distanceTo(aux[j]);
            if (distance < delta) {
                delta = distance;
                if (distance < bestDistance) {
                    bestDistance = delta;
                    best1 = aux[i];
                    best2 = aux[j];
                    // StdOut.println("better distance = " + delta + " from " + best1 + " to " + best2);
                }
            }
        }
    }
    return delta;
}
```



Matrix

multiplication

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \star \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} =$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \star \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} = \begin{bmatrix} 5 + 14 & 6 + 16 \\ 15 + 28 & 18 + 32 \end{bmatrix} \\ = \begin{bmatrix} 19 & 22 \\ 43 & 50 \end{bmatrix}$$

$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & & & \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix} \begin{bmatrix} b_{1,1} & b_{1,2} & \cdots & b_{1,n} \\ b_{2,1} & b_{2,2} & \cdots & b_{2,n} \\ \vdots & & & \\ b_{n,1} & b_{n,2} & \cdots & b_{n,n} \end{bmatrix} = \begin{bmatrix} c_{1,1} & c_{1,2} & \cdots & c_{1,n} \\ c_{2,1} & c_{2,2} & \cdots & c_{2,n} \\ \vdots & & & \\ c_{n,1} & c_{n,2} & \cdots & c_{n,n} \end{bmatrix}$$

$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & & & \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix} \begin{bmatrix} b_{1,1} & b_{1,2} & \cdots & b_{1,n} \\ b_{2,1} & b_{2,2} & \cdots & b_{2,n} \\ \vdots & & & \\ b_{n,1} & b_{n,2} & \cdots & b_{n,n} \end{bmatrix} = \begin{bmatrix} c_{1,1} & c_{1,2} & \cdots & c_{1,n} \\ c_{2,1} & c_{2,2} & \cdots & c_{2,n} \\ \vdots & & & \\ c_{n,1} & c_{n,2} & \cdots & c_{n,n} \end{bmatrix}$$

$$c_{i,j} = \sum_{k=1}^n a_{i,k} \cdot b_{k,j}$$

$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & & & \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix} \begin{bmatrix} b_{1,1} & b_{1,2} & \cdots & b_{1,n} \\ b_{2,1} & b_{2,2} & \cdots & b_{2,n} \\ \vdots & & & \\ b_{n,1} & b_{n,2} & \cdots & b_{n,n} \end{bmatrix} = \begin{bmatrix} c_{1,1} & c_{1,2} & \cdots & c_{1,n} \\ c_{2,1} & c_{2,2} & \cdots & c_{2,n} \\ \vdots & & & \\ c_{n,1} & c_{n,2} & \cdots & c_{n,n} \end{bmatrix}$$

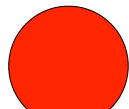
$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} E & F \\ G & H \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} E & F \\ G & H \end{bmatrix} = \begin{bmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} E & F \\ G & H \end{bmatrix} = \begin{bmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{bmatrix}$$

$$T(n) = 8T(n/2) + \Theta(n^2)$$

$$\Theta(n^3)$$



$$= \begin{bmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{bmatrix}$$

[Strassen]

$$P_1 = A(F - H)$$

$$P_2 = (A + B)H$$

$$P_3 = (C + D)E$$

$$P_4 = D(G - E)$$

$$P_5 = (A + D)(E + H)$$

$$P_6 = (B - D)(G + H)$$

$$P_7 = (A - C)(E + F)$$

$$=R \left[\begin{array}{l} \frac{AE + BG}{P_5 + P_4 - P_2 + P_6} \quad AF + BH \quad S \\ \frac{CE + DG}{T = P_3 + P_4} \quad CF + DH \\ U = P_5 + P_1 - P_3 \end{array} \right] = P_1 + P_2 - P_7$$

[strassen]

$$P_1 = A(F - H)$$

$$P_2 = (A + B)H$$

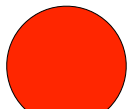
$$P_3 = (C + D)E$$

$$P_4 = D(G - E)$$

$$P_5 = (A + D)(E + H)$$

$$P_6 = (B - D)(G + H)$$

$$P_7 = (A - C)(E + F)$$



$$=R \left[\begin{array}{cc} \frac{AE + BG}{P_5 + P_4 - P_2 + P_6} & \frac{AF + BH}{S} \\ \frac{CE + DG}{T = P_3 + P_4} & \frac{CF + DH}{U = P_5 + P_1 - P_3} \end{array} \right] = P_1 + P_2 - P_7$$

[strassen]

$$P_1 = A(F - H)$$

$$P_2 = (A + B)H$$

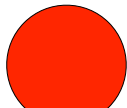
$$P_3 = (C + D)E$$

$$P_4 = D(G - E)$$

$$P_5 = (A + D)(E + H)$$

$$P_6 = (B - D)(G + H)$$

$$P_7 = (A - C)(E + F)$$



$$=R \left[\begin{array}{cc} AE + BG & AF + BH \\ CE + DG & CF + DH \end{array} \begin{array}{c} S \\ T \\ U \end{array} \right] = P_1 + P_2$$

$P_5 + P_4 - P_2 + P_6$ $P_3 + P_4$ $P_5 + P_1 - P_3 - P_7$

[strassen]

$$P_1 = A(F - H)$$

$$P_2 = (A + B)H$$

$$P_3 = (C + D)E$$

$$P_4 = D(G - E)$$

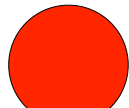
$$P_5 = (A + D)(E + H)$$

$$P_6 = (B - D)(G + H)$$

$$P_7 = (A - C)(E + F)$$

$$M(n) = 7M(n/2) + 18n^2$$

$$= \Theta(n^{\log_2 7})$$



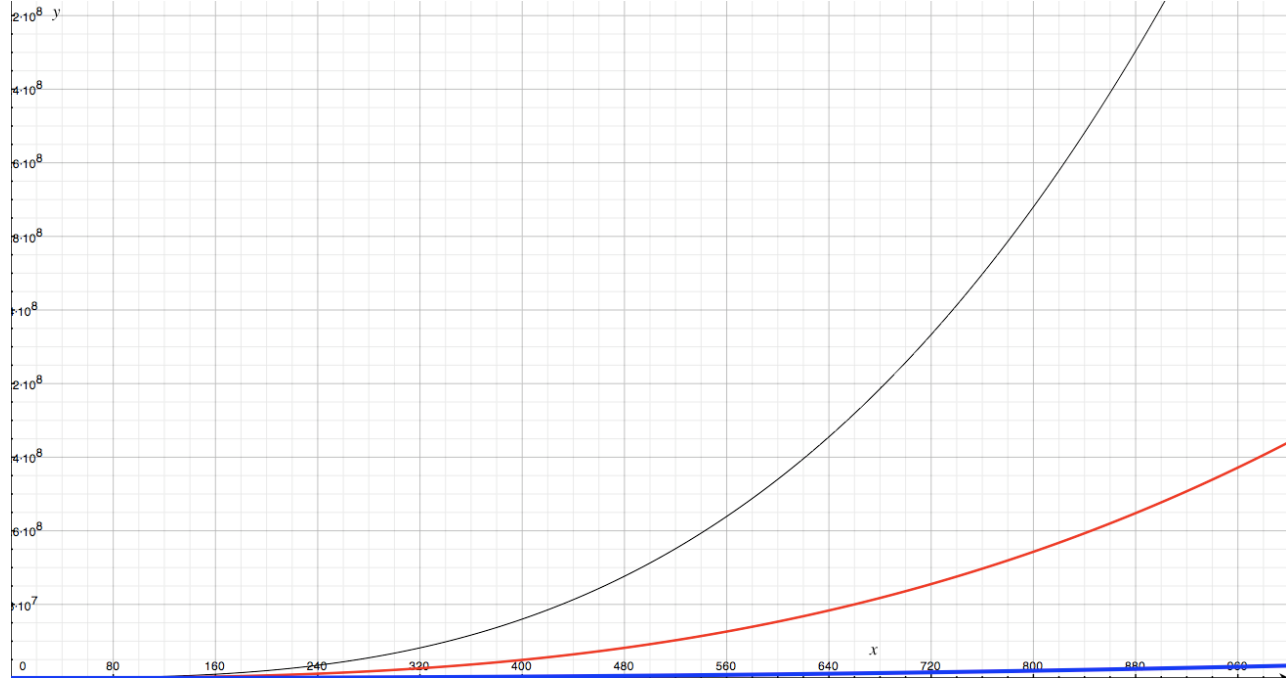
taking this idea further

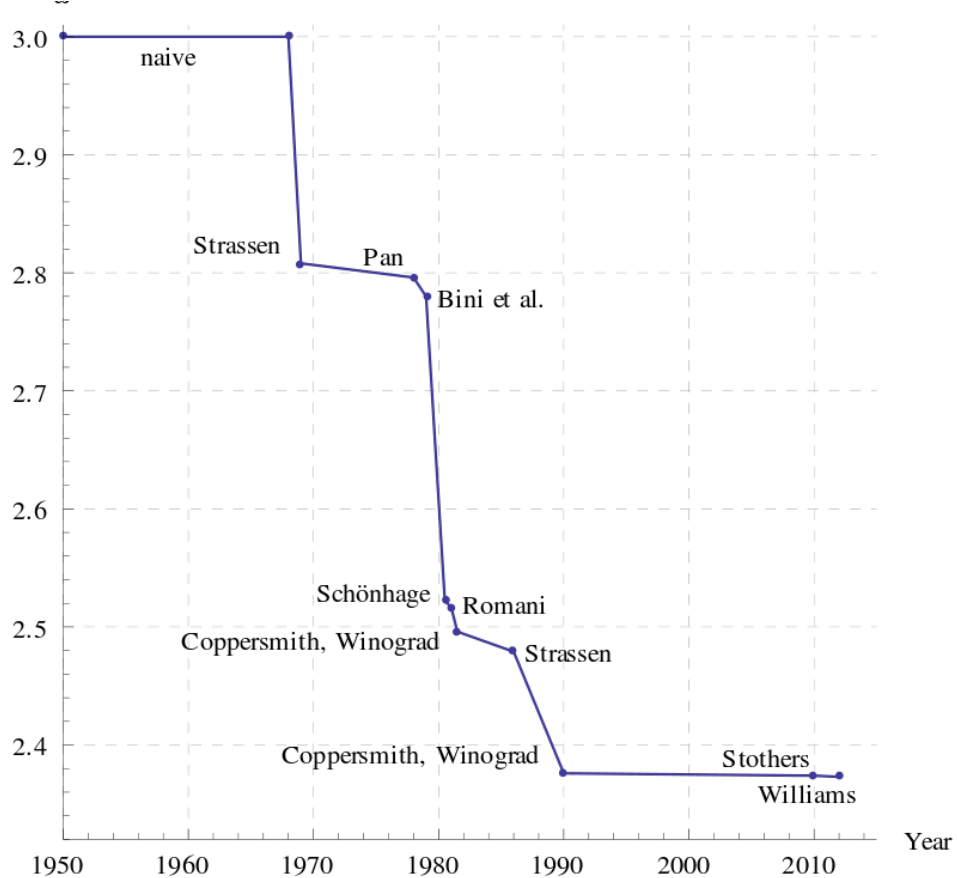
3x3 matrices [Laderman'75]

1978 victor pan method

70x70 matrix using 143640
mults

what is the recurrence:





MEDIAN



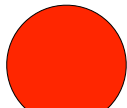
problem: given a list of n elements, find the element of rank $n/2$. (half are larger, half are smaller)



problem: given a list of n elements, find the element of rank $n/2$. (half are larger, half are smaller)
can generalize to i

first solution: sort and pluck.

$$O(n \log n)$$

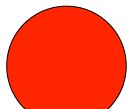




problem: given a list of n elements, find the element of rank i .

key insight:

**we do not have to “fully” sort.
semi sort can suffice.**





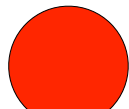
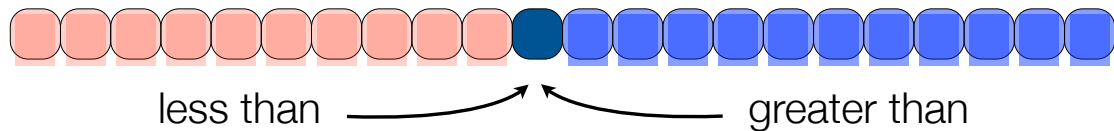
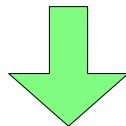
pick first element
partition list about this one
see where we stand

review: how to partition a list





GOAL: start with THIS LIST and END with THAT LIST



review: how to partition a list

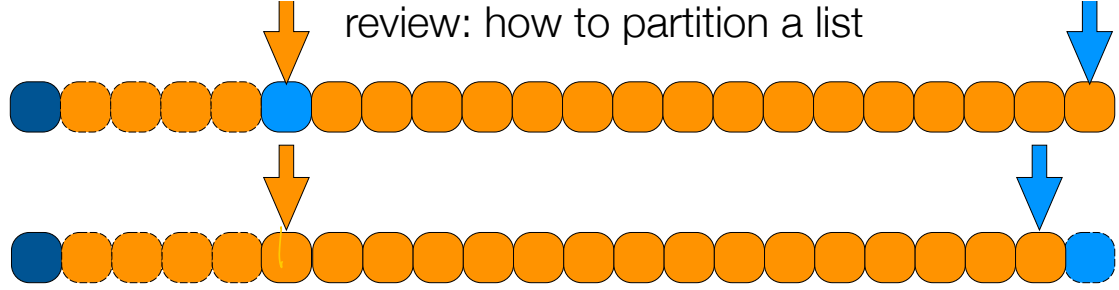


review: how to partition a list

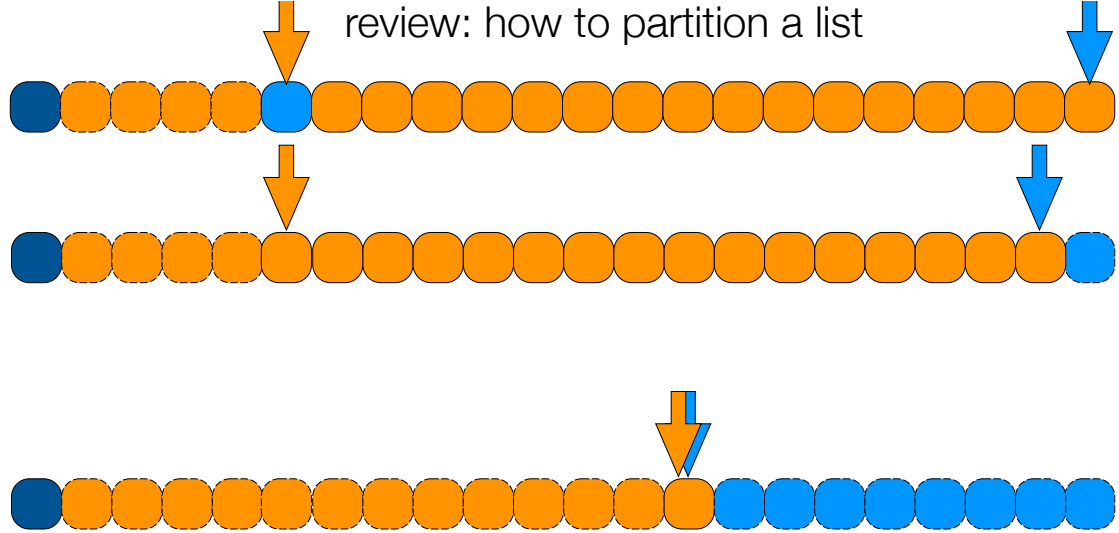
Step



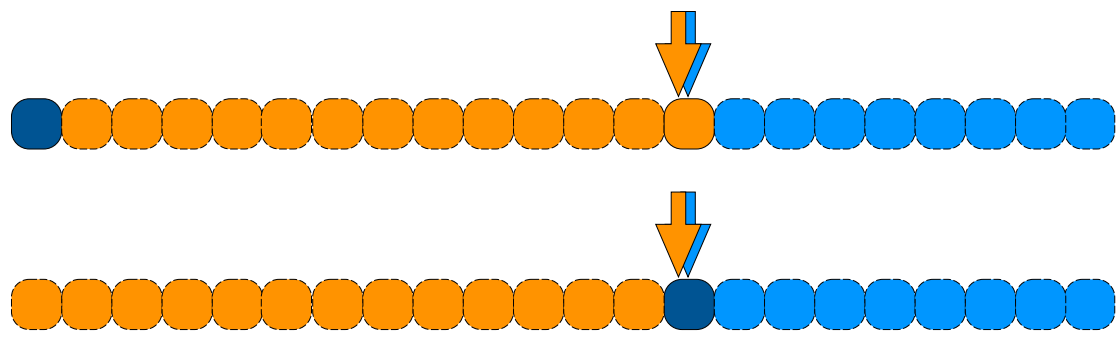
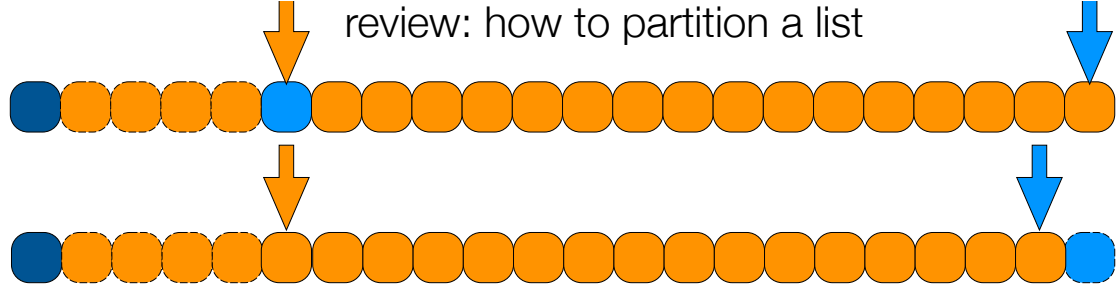
review: how to partition a list



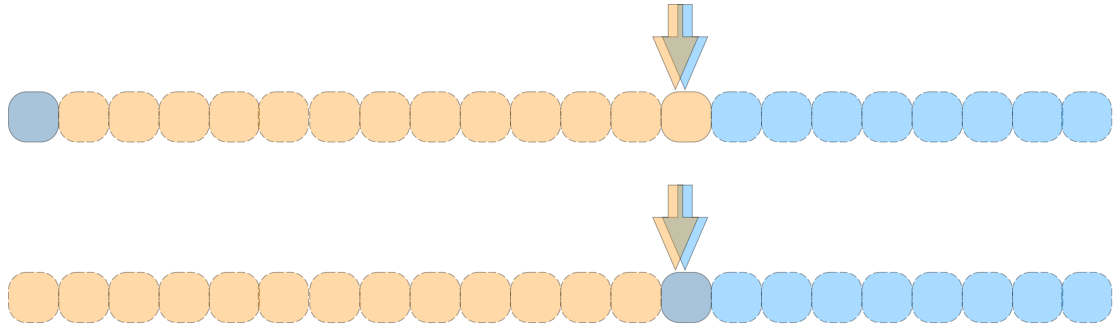
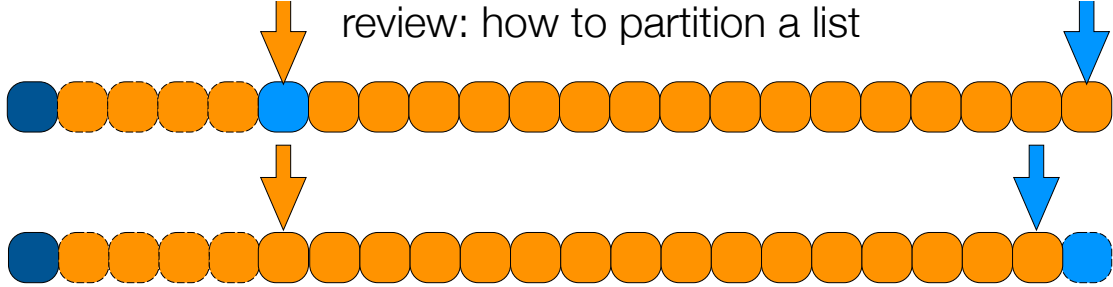
review: how to partition a list



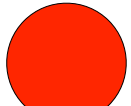
review: how to partition a list

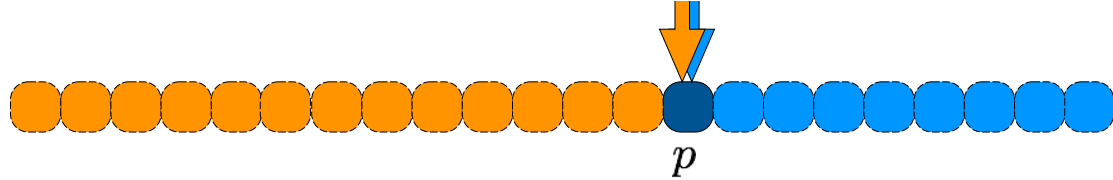


review: how to partition a list

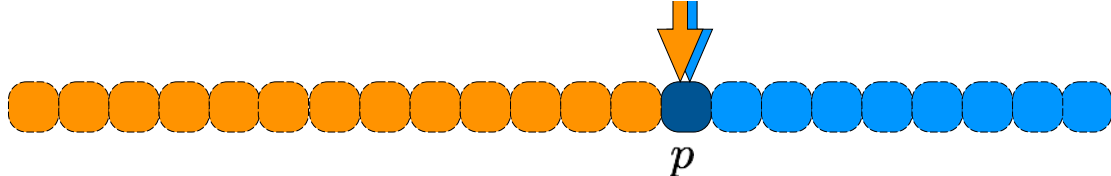


partitioning a list about an element takes linear time.





select ($i, A[1, \dots, n]$)



select ($i, A[1, \dots, n]$)

handle base case.

partition list about first element

if pivot p is position i , return pivot

else if pivot p is in position $> i$ **select** ($i, A[1, \dots, p - 1]$)

else **select** ($(i - p - 1), A[p + 1, \dots, n]$)

select ($i, A[1, \dots, n]$)

Assume our partition always
splits list into two eql parts

handle base case.

partition list about first element

if pivot is position i , return pivot

else if pivot is in position $> i$ select ($i, A[1, \dots, p - 1]$)

else select ($(i - p - 1), A[p + 1, \dots, n]$)

select ($i, A[1, \dots, n]$)

Assume our partition always
splits list into two eqal parts

handle base case.

partition list about first element

if pivot is position i , return pivot

else if pivot is in position $> i$ select ($i, A[1, \dots, p - 1]$)

else select ($(i - p - 1), A[p + 1, \dots, n]$)

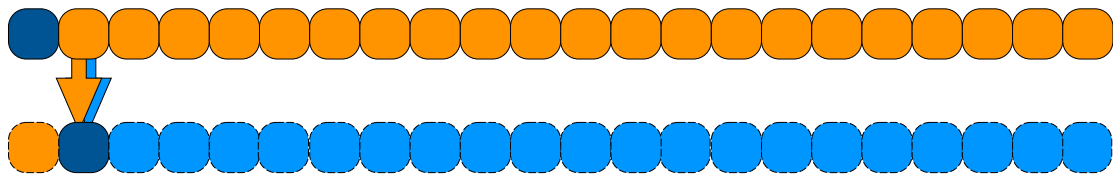
$$T(n) = T(n/2) + O(n)$$

$$\Theta(n)$$

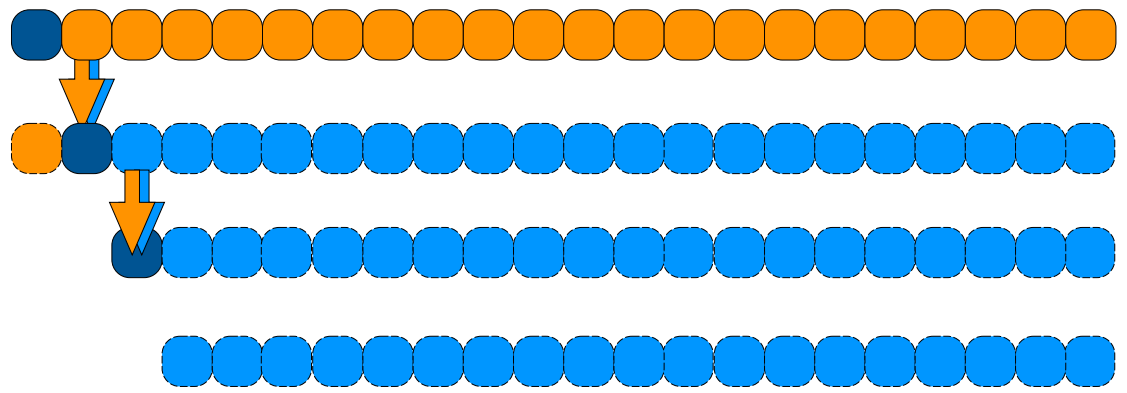
problem: what if we always pick bad partitions?

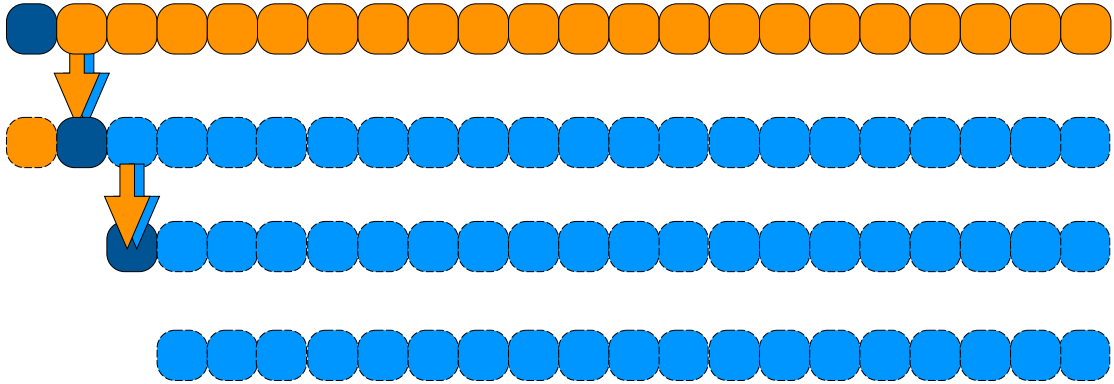


problem: what if we always pick bad partitions?

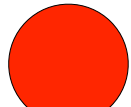


problem: what if we always pick bad partitions?





problem: what if we always pick bad partitions?



`select` ($i, A[1, \dots, n]$)

handle base case.

partition list about first element

if pivot is position i , return pivot

else if pivot is in position $> i$ `select` ($i, A[1, \dots, p - 1]$)

else `select` ($(i - p - 1), A[p + 1, \dots, n]$)

select ($i, A[1, \dots, n]$)

handle base case.

partition list about first element

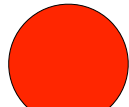
if pivot is position i , return pivot

else if pivot is in position $> i$ select ($i, A[1, \dots, p - 1]$)

else select ($(i - p - 1), A[p + 1, \dots, n]$)

$$T(n) = T(n - 1) + O(n)$$

$$\Theta(n^2)$$



Needed:

a good partition element

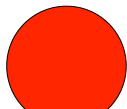
partition ($A[1, \dots, n]$)

Needed:

a good partition element

partition ($A[1, \dots, n]$)

produce an element where
30% smaller, 30% larger



solution:
bootstrap



image: mark nason



image: gucci



image: d&g

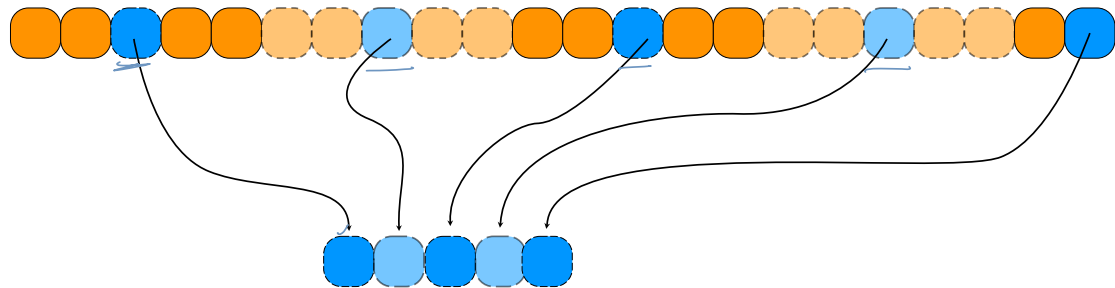
partition ($A[1, \dots, n]$)

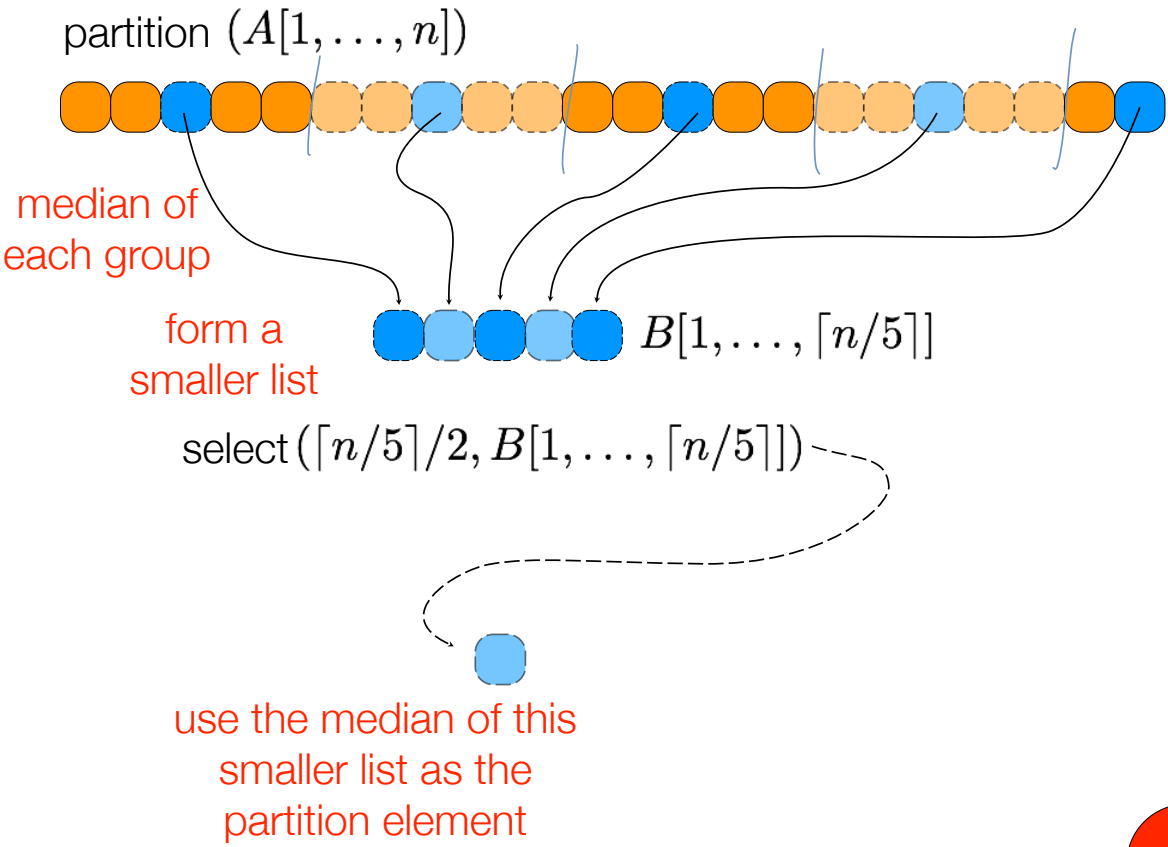


partition ($A[1, \dots, n]$)



partition ($A[1, \dots, n]$)





partition ($A[1, \dots, n]$)



- 1.
- 2.
- 3.
- 4.
- 5.

partition ($A[1, \dots, n]$)



divide list into groups of 5 elements

find median of each small list

gather all medians

call `select(...)` on this sublist to find median

return the result

partition ($A[1, \dots, n]$)



divide list into groups of 5 elements

find median of each small list

gather all medians

call select(...) on this sublist to find median

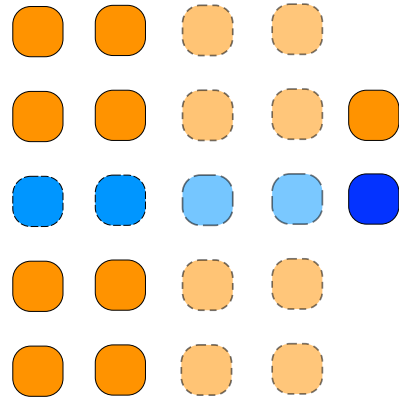
return the result

$$P(n) = S(\lceil n/5 \rceil) + O(n)$$

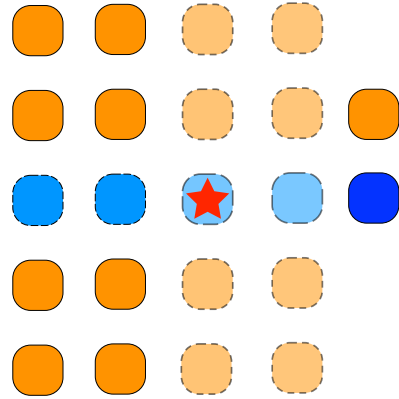
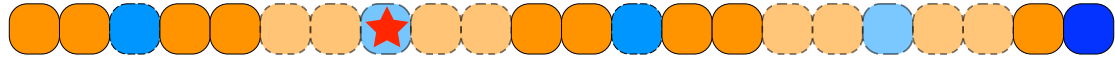
a nice property of our partition



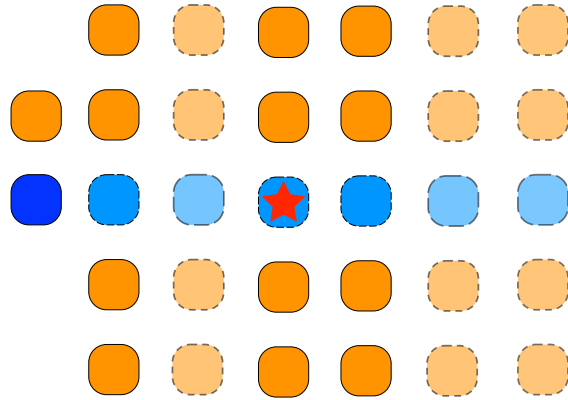
a nice property of our partition



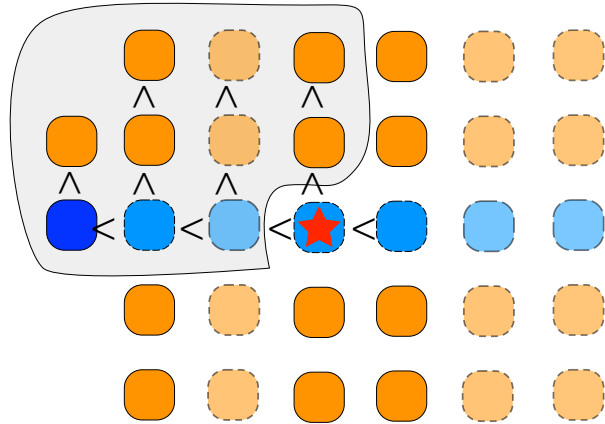
a nice property of our partition



SWITCH TO A BIGGER EXAMPLE

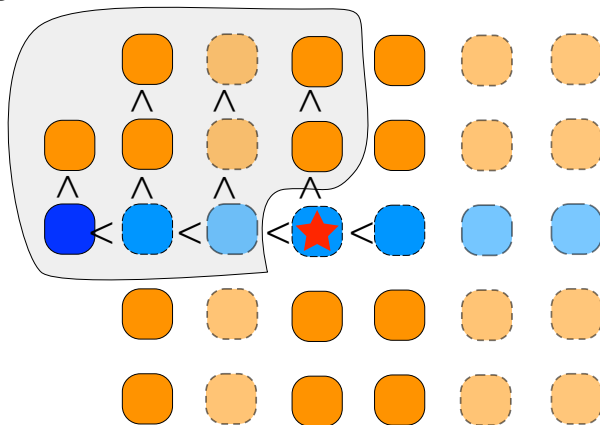


a nice property of our partition



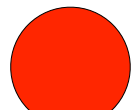
a nice property of our partition

$$3 \left(\left\lceil \frac{1}{2} \lceil n/5 \rceil \right\rceil - 2 \right) \geq \frac{3n}{10} - 6$$



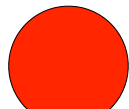
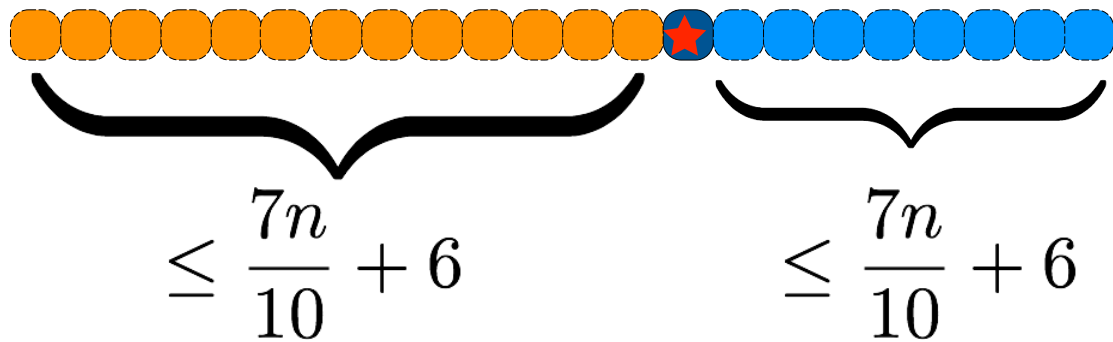
this implies there are
at most $\frac{7n}{10} + 6$ numbers

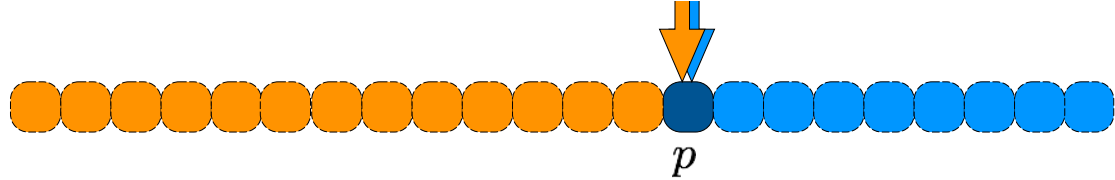
larger than ★
/smaller



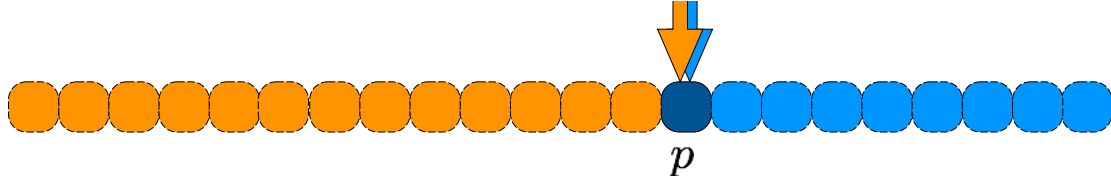
a nice property of our partition







select ($i, A[1, \dots, n]$)



`select` ($i, A[1, \dots, n]$)

handle base case for small list

else `pivot` = `FindPartitionValue(A,n)`

partition list about `pivot`

if `pivot` is position i , return `pivot`

else if `pivot` is in position $> i$ `select` ($i, A[1, \dots, p - 1]$)

else `select` ($(i - p - 1), A[p + 1, \dots, n]$)

FindPartition ($A[1, \dots, n]$)



divide list into groups of 5 elements

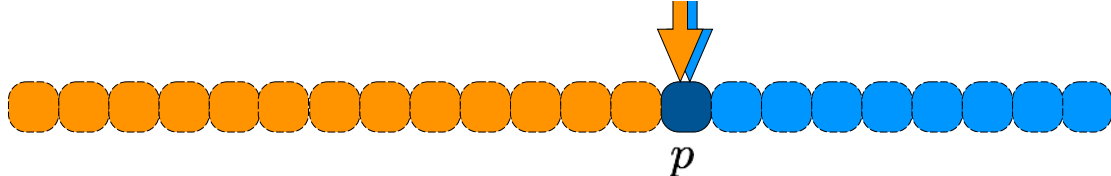
find median of each small list

gather all medians

call select(...) on this sublist to find median

return the result

$$P(n) = S(\lceil n/5 \rceil) + O(n)$$



`select` ($i, A[1, \dots, n]$)

handle base case for small list

else `pivot` = `FindPartitionValue(A,n)`

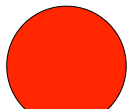
partition list about `pivot`

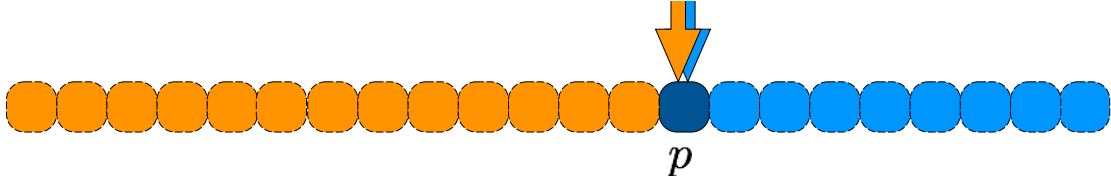
if `pivot` is position i , return `pivot`

else if `pivot` is in position $> i$ `select` ($i, A[1, \dots, p - 1]$)

else `select` ($(i - p - 1), A[p + 1, \dots, n]$)

$$S(n) = S(\lceil n/5 \rceil) + O(n) + S(7n/10 + 6)$$





`select` ($i, A[1, \dots, n]$)

handle base case for small list

else `pivot` = `FindPartitionValue(A,n)`

partition list about `pivot`

if `pivot` is position i , return `pivot`

else if `pivot` is in position $> i$ `select` ($i, A[1, \dots, p - 1]$)

else `select` ($((i - p - 1), A[p + 1, \dots, n])$)

$$S(n) = S(\lceil n/5 \rceil) + O(n) + S(7n/10 + 6)$$

$$\Theta(n)$$

